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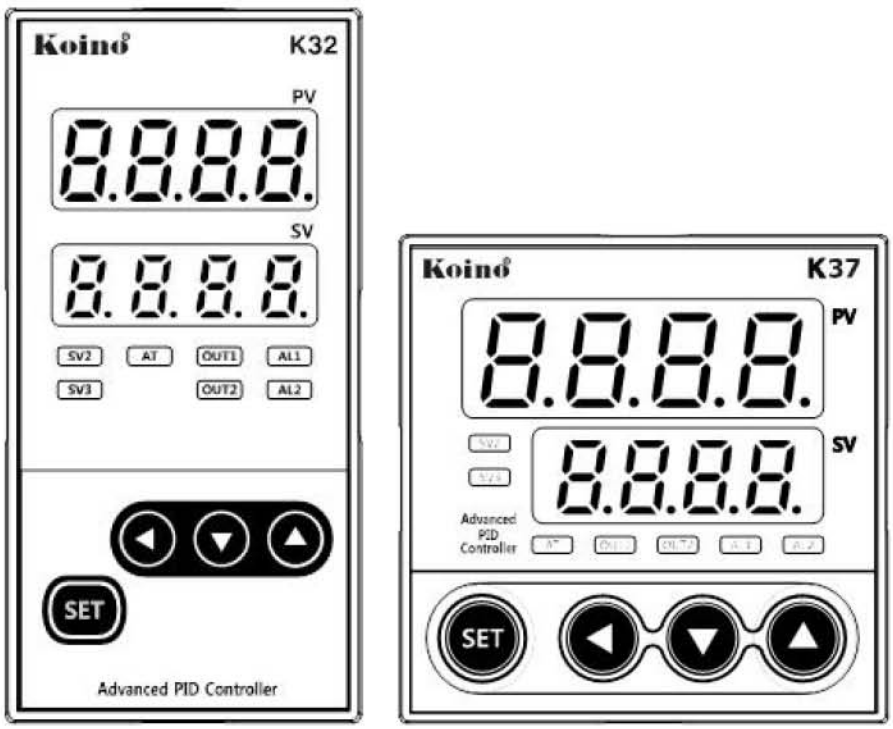
MICRO COMPUTER

Digital PID Controller User' s Manual

K30–SERIES



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Preface

Thank you for purchasing the K30 series from Koino.
The K30 series is a precision industrial controller that uses an advanced 2 degree-of-freedom (DOF) algorithm.
The K30 series consists of 5 models, which are K32, K33, K34, K37, and K39.
This manual explains the installation, the functions, the operation, and the handling of the products.
Please read the manual thoroughly before using the products.
If any difficulties arise while using our products, please call our customer service at +82-2-2242-1275.

Pay attention to the followings!

- Use the products under the conditions specified in this manual.
- Please heed the cautions and warnings listed in this manual.
- The contents of the manual may be changed without notice.
- The product is designed to be used installed on a control panel.
- This manual is copyrighted, and may not be copied in part or in whole without permission.
- The manufacturer takes no responsibility for direct or indirect damages caused by careless operation or operation under unpredictable or risky environments

Safety requirements!

Safety requirements are intended to prevent accidents and dangers through the proper use of the products, so please heed them at all times.
The safety requirements are divided into **"cautions"** and **"warnings"**, which indicate the following.

⚠ WARNING

Serious injury or death may be caused if instructions are not observed.

⚠ CAUTION

Failure to observe these instructions may cause damage to the instrument or some injury to the user.

⚠ WARNING

1. Use a separate safety device when this product is used to control a device that could harm lives or expensive property in the event of a malfunction or a breakdown. (This may cause fires, deaths, or damage to property)
2. Do not use this controller at place where there are flammable or explosive gas. (It may cause a fire or explosion.)
3. Before turning the power on, please check that wiring is correct to the number of terminal. (It may cause a fire)
4. Turn off the power during wiring and maintenance to avoid an electric shock.
5. Do not touch the terminals when it is power on. (It may give an electric shock.)
6. This controller must be mounted on the panel to avoid an electric shock.
7. Do not attempt to disassemble, modify and repair.

⚠ CAUTION

1. Please conduct an inspection when water has entered the product. (It may cause short circuits, fires, and malfunction.)
2. This controller should be used indoors. (It may shorten the controller' s life or give an electric shock.)
3. Observe the rated voltage and specification. (It may cause a fire or shorten the controller' s life.)
4. Be careful that any of foreign materials do not inflow into the controller. (It may cause a fire or malfunction of the controller.)
5. Do not give direct vibration or shock to the controller. (It may cause of malfunction of the controller.)
6. Do not use chemical detergent or solvent, but use a dry towel in cleaning the controller. (It may cause an electric shock or a fire.)
7. Please check the polarity of power before wiring and connecting the sensor. (It may cause an electric shock or explosion.)

Contents

K3 □ – □ □ □

④ Power supply voltage
③ Optional function
② Control mode
① Size

① Size

Code	Model	Size	Remarks
2	K32–SERIES	48(W) × 96(H) × 77(D)	No option (Basic function)
3	K33–SERIES	96(W) × 48(H) ×77(D)	No option (Basic function)
4	K34–SERIES	48(W) × 48(H) ×99(D)	Option : 0, 1, 2, 3
7	K37–SERIES	72(W) × 72(H) ×77(D)	Option : 0, 3
9	K39–SERIES	96(W) × 96(H) × 77(D)	No option (Basic function)

② Control mode

Code	Description	Remarks
S	SINGLE : Standard	Heating or Cooling control

④ Power supply voltage

Code	Description	Remarks
0	100 ~ 240 V AC	General–purpose usage
1	24 V AC or DC	Alternating or Direct current usage

③ Optional function

Model	Code	Description	Remarks
K32, K33 SERIES	Basic function (0)	RELAY output 1, Alarm output 2,	No function (Basic function S0x)
		SCR(4~20mA), SSR(Voltage pulse) 1,	
		RET(4~20mA Retransmission output)	
		D.I(SV2, 3) External input	
K34 SERIES	Basic function (0)	RELAY output 1 (ALARM or MAIN),	Basic function + Option code (0 : No option)
		SCR(4~20mA), SSR(Voltage pulse) 1	
	1	RET(4~20mA Retransmission), Alarm 2	Ex) K34-S10
	3	D.I(SV2, 3) External input, Alarm output 2	Ex) K34-S30
K37 SERIES	Basic function (0)	RELAY output 1, Alarm output 2,	Basic function + Option code (0 : No option)
		SCR(4~20mA), SSR(Voltage pulse) 1	
	3	D.I(SV2, 3), RET(4~20mA Retransmission)	Ex) K37-S30
K39 SERIES	Basic function (0)	RELAY output 1, Alarm output 2,	Basic function + Option code (0 : No option)
		SCR(4~20mA), SSR(Voltage pulse) 1,	
		RET(4~20mA Retransmission)	

Example of model building

K34-S00

① Size : 48(W) × 48(H) × 99(D) ☞ "4"
② Control mode : SINGLE ☞ "S"
③ Optional function : Basic function ☞ "0"
④ Supply voltage : 100~240V AC ☞ "0"

→ **K34-S00**

K37-S30

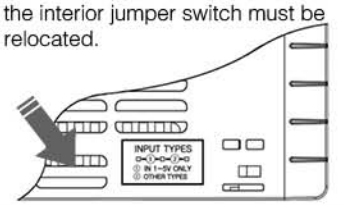
① Size : 72(W) × 72(H) × 77(D) ☞ "7"
② Control mode : SINGLE ☞ "S"
③ Optional function : DI(SV1,2), RET ☞ "3"
④ Supply voltage : 100~240V AC ☞ "0"

→ **K37-S30**

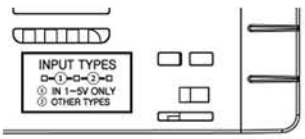
2. Input ranges and output constitutions

2–1. Input ranges

※ The K30 series has multiple inputs, which may be set and changed by the user.

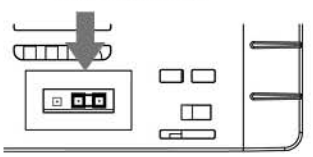
Input type	Signal	Setting Code	Temperature range	Accuracy	Remarks
Thermocouple (T.C)	K	1	–200 ~ 1370	± 0.3% of F.S +1Digit	* F.S is max. value to min. value of each range * Digit is minimum of display ① 0~400℃ range : ± 10% of F.S+1Digit
		2	–199.9 ~ 999.9		
	J	15	–200 ~ 1000		
		3	–199.9 ~ 999.9		
	E	16	–200 ~ 1000		
		4	199.9 ~ 999.9		
	T	5	–199.9 ~ 400.0		
	R	6	0 ~ 1700		
	B ①	7	0 ~ 1800		
	S	8	0 ~ 1700		
	L	17	–200 ~ 900		
		9	–199.9 ~ 900.0		
	N	10	–200 ~ 1300		
	U	11	–199.9 ~ 400.0		
	C (W5)	12	0 ~ 2300		
	D (W3)	13	0 ~ 2400		
RTD	JPt100 Ω (JIS,KS)	20	–199.9 ~ 500.0		
		22	–200 ~ 500		
	Pt100 Ω (DIN,IEC)	21	–199.9 ~ 640.0		
		23	–200 ~ 640		
Voltage (VDC/mVDC)	0~100 mV DC	33	0 ~ 100mV DC		
	–10~20 mV DC	32	–10 ~ 20 mV DC		
	1~5V DC	30	1~5V DC	※ When using 1~5V input (30), the interior jumper switch must be relocated. 	
Current	4~20mA DC	30	When using current input, use the resistor 250Ω on input terminal.		

How to change the interior switch when using 1~5V input



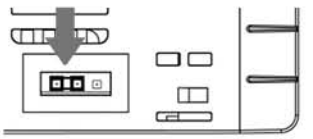
① Remove the jumper cover on the underside of the K30, or remove the rear case.

OTHER TYPES



② Detach the jumper using tweezers and move it to the 1–2 pins to the left.

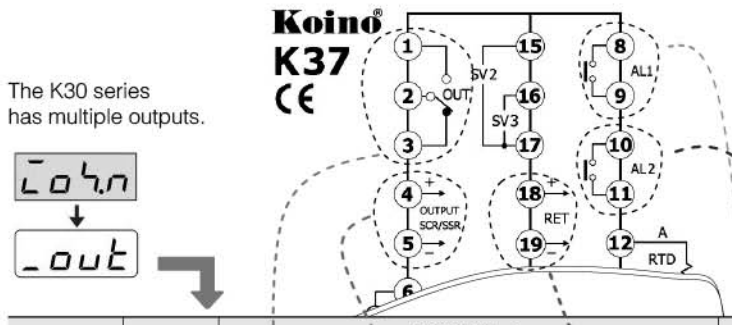
1~5V DC INPUT ONLY



③ Once this has been com–pleted, put the jumper cover back on, as shown on the picture above.

2–2. Output constitutions

The K30 series has multiple outputs.



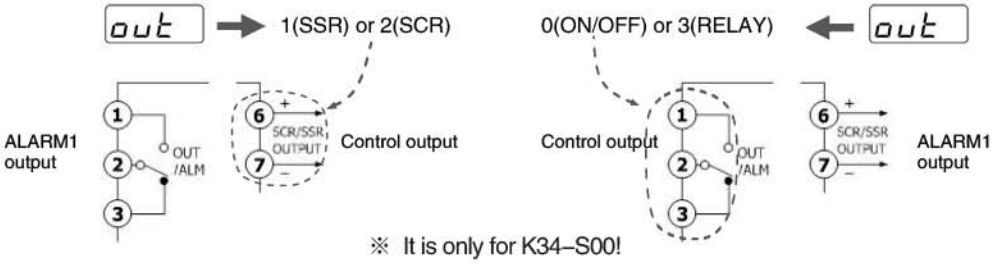
※ The figure on the left uses the terminal socket of K37–S30 as an example to illustrate the output response relationship.

General type	Setting number	OUTPUT–1			OUTPUT–2 (ALARM1,2)		
		Relay output	SSR/SCR OUTPUT		AL1	AL2	SCR output
			SSR output	SCR output			
K30–Sxx	0	OUT(ON/OFF)	ALM1(34–S0x)	–	ALARM1	ALARM2	RET
	1	ALM1(34–S0x)	OUT(PID)	–			
	2	ALM1(34–S0x)	–	OUT(PID)			
	3	OUT(PID)	ALM1(34–S0x)	–			

Summary and explanation of output settings

- Relay output of ON/OFF control [Output setting number : 0]
  This is a simple on/off control, mainly used to control cooling devices.
- SSR output of PID control (Voltage pulse) [Output setting number : 1]
  This is the most widely used setting, and the default value at the point of manufacture.
- SCR output of PID control (4~20mA current output) [Output setting number : 2]
  This setting is used mainly with thyristor power regulator (TPR) modules, and is capable of precision control.
- Relay output of PID control [Output setting number : 3]
  This is the most cost–efficient method of implementing PID control and is used mainly with magnetic switches (electric switches). However, it may wear the contact point, and is difficult to use in places that require fast response.

Alarm output of K34(48′48) basic type(S00)

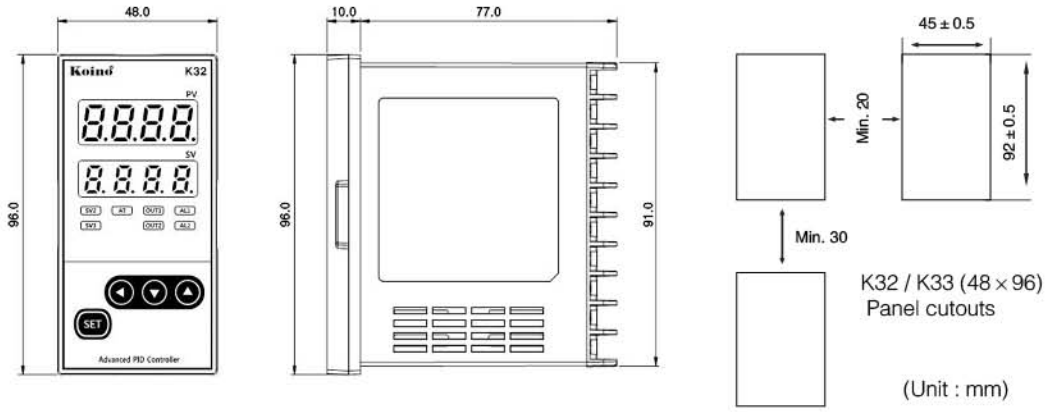


※ It is only for K34–S00!

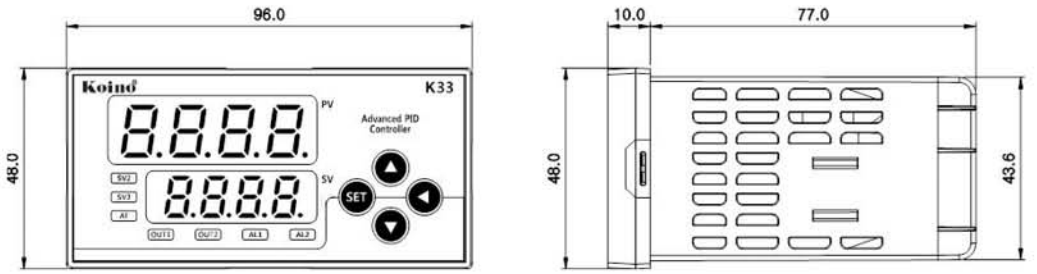
With the basic model of K34 (48x48), caution is required when using it alarm output. When control output is being used as a relay, the alarm output will be SSR output (voltage pulse). In this case, use SSR or alarm option (S10, S30) enabled models.

3. Dimensions and panel cutouts

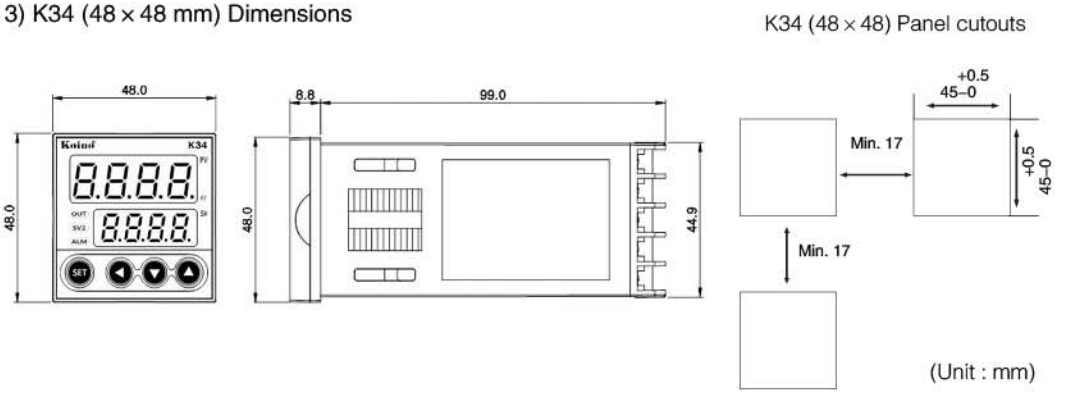
1) K32 (48 × 96 mm) Dimensions



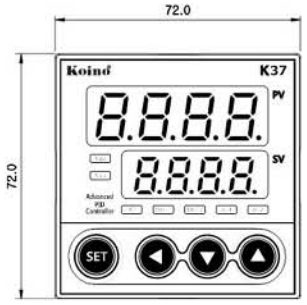
2) K33 (96 × 48 mm) Dimensions

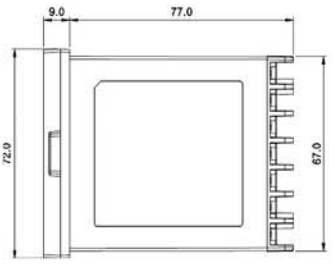


3) K34 (48 × 48 mm) Dimensions

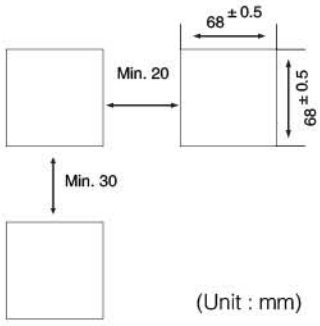


4) K37 (72 × 72 mm) Dimensions



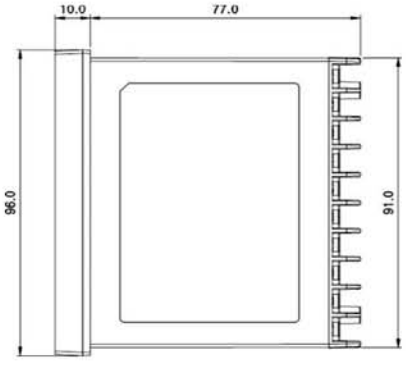


K37 (72 × 72) Panel cutouts

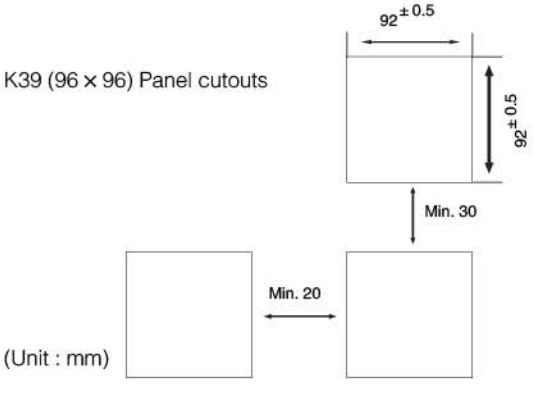


(Unit : mm)

5) K39 (96 × 96 mm) Dimensions



K39 (96 × 96) Panel cutouts

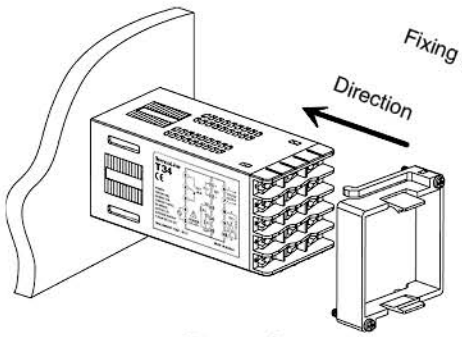


(Unit : mm)

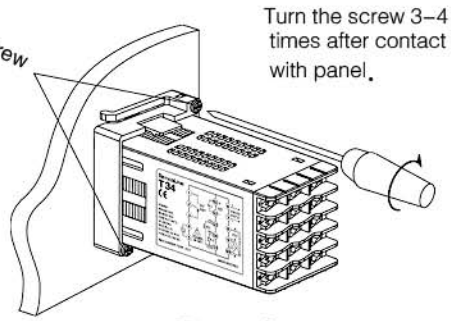
Installation

■ K34–SERIES

① Bore a hole in the panel, referring to the panel cutouts on the previous page.
② Insert this device into the front of the panel.
③ From the rear of controller, slide the bracket over the housing.
④ Push the bracket in until the device has been fixed securely onto the panel.
⑤ Secure using screws on the two locations at top and bottom as shown on Figure 2.



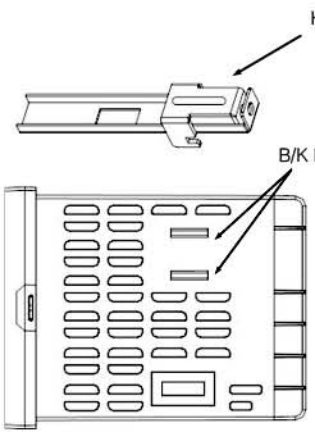
[Picture 1]



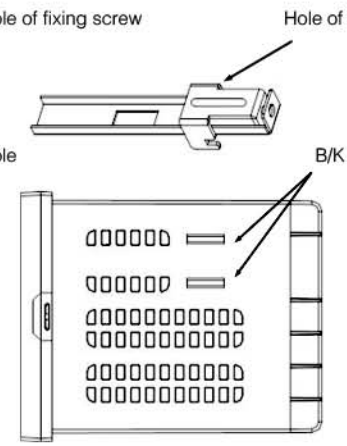
[Picture 2]

■ K32 / K33 / K37 / K39–SERIES

① Bore a hole in the panel, referring to the panel cutouts on the previous page.
② Insert this device into the front of the panel.
③ Insert 2 brackets, one each on the B/K holes on the top and the bottom of the device.
④ Secure using screws on the two locations at top and bottom.



[Picture 1] Top side

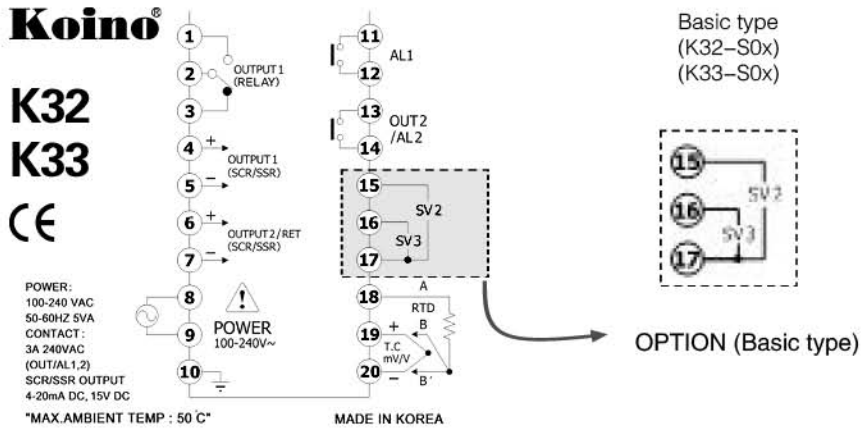


[Picture 2] Bottom side

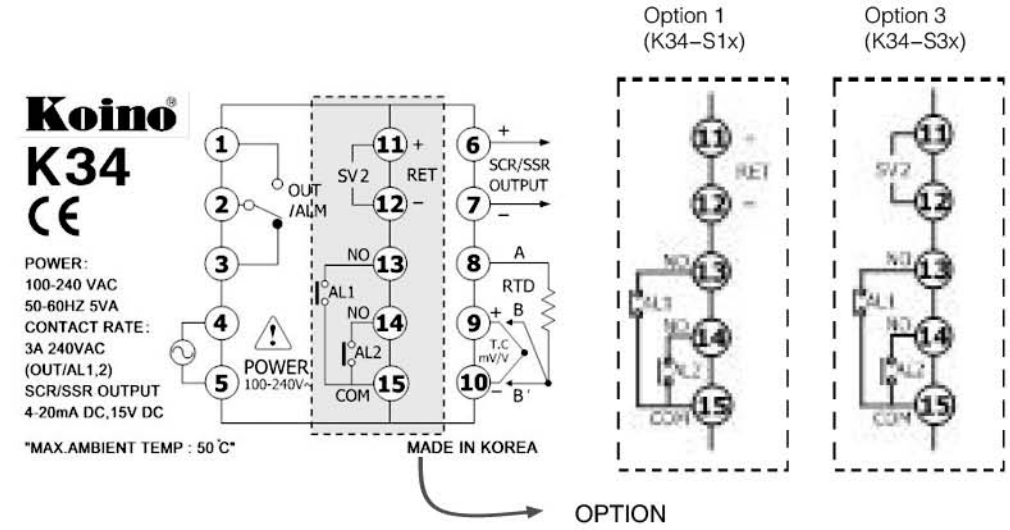
[Picture 3] Fixing completion

4. Terminal arrangements and wirings

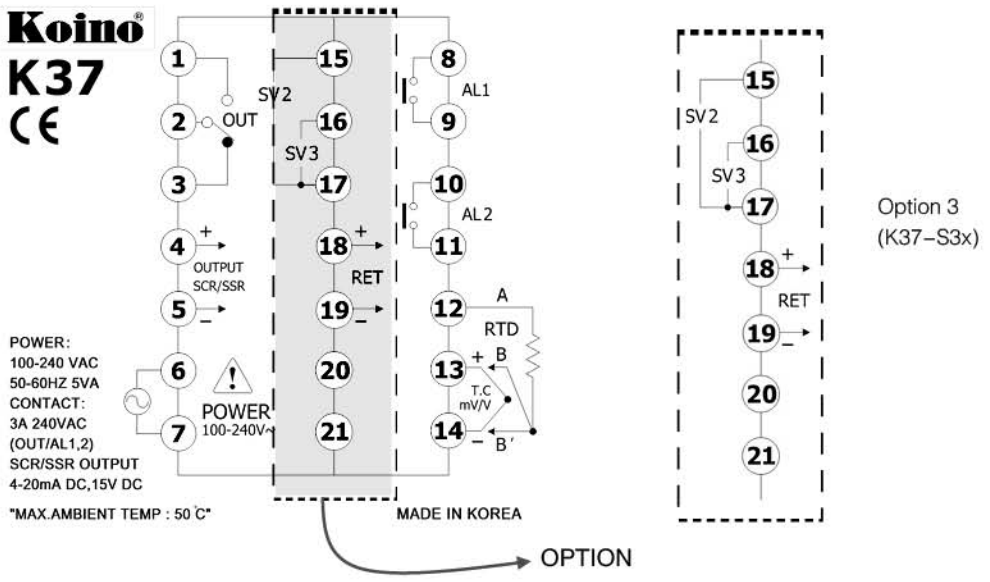
1) K32 (48 × 96 mm), K33 (96 × 48 mm)



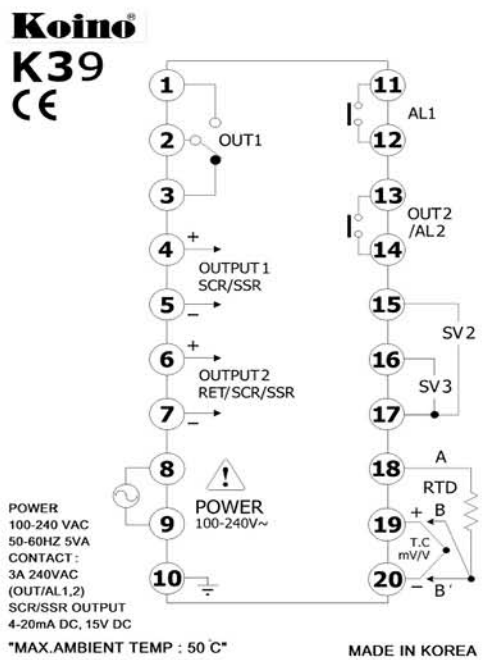
2) K34 (48 × 48mm)



3) K37 (72 x 72 mm)



4) K39 (96 x 96 mm)



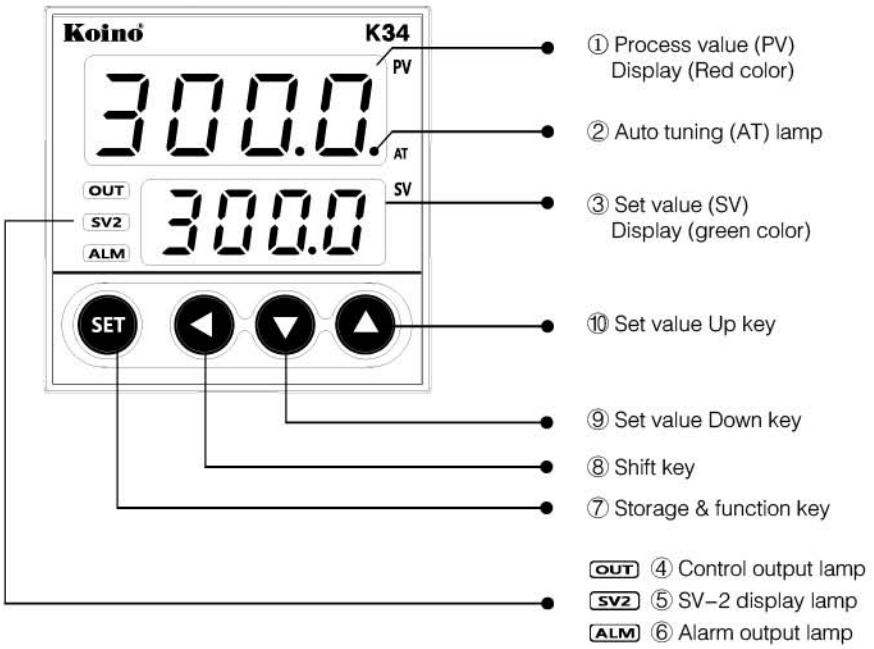
Terminal explanation (K39-S00)

- Terminal (1)-(2)-(3) : OUT1 only for output selection no. 0, 3 (Relay output) mode.
- Terminal (4)-(5) : OUT2 only for output. selection no. 1, 2 (SSR, SCR output) mode.
- Terminal (6)-(7) : RET(Retransmission 4~20mA) or for power of sensor SPS. (DC 15V)
- Terminal (8)-(9) : Power supply terminal.
- Terminal (11)-(12) : Alarm1 output terminal.
- Terminal (13)-(14) : Alarm2 output terminal.
- Terminal (15)-(16)-(17) : The external D.I input terminal may be used when (DIS=ON), and the target value may be controlled. (SV1, SV2, SV3)
- Terminal (18)-(19)-(20) : Input terminals.

5. Ratings and specifications

Model		K30-SERIES
Power supply		100~240V AC 50~60Hz (Operating voltage range 85~265V AC) 24V AC or DC (Operating voltage range 20~28V DC)
Power consumption		6VA (Max.)
Sensor input		Thermocouple (TC) : K, J, T, E, R, B, S, L, N, U, C(W5), D(W3) Resistance temp. detector (RTD) : KPt100(KS), JPt100(JIS), Pt100(DIN) Current input : 4~20mA DC Voltage input : 1~5V DC, -10~20mV DC, 0~100mV DC
Accuracy		±0.3% of FS +1Digit
Input impedance		Current input (250Ω), Voltage input (including TC) 1MΩ min. (RTD allowable wiring resistance : 10Ω max., but, 3 wires have a equal resistance)
Input sampling period		250ms (changeable according to SG-PID algorithm)
Control output	Relay	1c 250VAC, 3A(resistive load) Electrical life 100,000 min. (PID output or ON/OFF output)
	Voltage (S.S.R)	DC15V 25mA (Built-in short protection circuit) Voltage pulse (PID output)
	Current (S.C.R)	4~20mA DC, allowable load impedance 600Ω max. (PID output)
Control type		Super 2 degree-of-freedom PID (SG-PID algorithm), S-Fuzzy, Auto-Tuning
Digital Input		ON : 1KΩ max., OFF : 100KΩ min. (SV1, 2, 3 external control input)
Retransmission output		4~20mA DC, allowable load impedance 600Ω or less. Resolution 1/4600 PV, SV, MV[%], SPS
Alarm	ALARM1, 2	1a 250V AC 3A (Resistive load)
	HBA(C.T) com.	HBA : 1~50A AC (Resolution 0.5A)
Ambient temperature and humidity		-10~50℃ / 25~85% RH (with no condensation or icing)
Weight (incl. B/K & accessories)		● K32, K33, K37-SERIES : 230g ● K34 : 140g ● K39 : 320g ※ When option + 30g

6. Name & Function (ex. K34–SERIES)



◆ Description

Name	Function
① Process value	Display the process value. (red color)
② Auto tuning lamp	Flash every 0.5 second during auto tuning.
③ Set value display	Display the set value, codes, and modes.
④ Control output lamp	Lights when the control output is ON.
⑤ SV–2 display lamp	Lights when the SV 2 is displayed.
⑥ Alarm output lamp	Lights during the alarm is ON.
⑦ SET Function key	Use to move the menus, to store, and to operate.
⑧ ◀ Shift key	Use to shift the digits.
⑨ ▼ Set value down key	Use to decrease set value and to move the menu.
⑩ ▲ Set value up key	Use to increase set value and to move the menu.

7. Check Points before Using

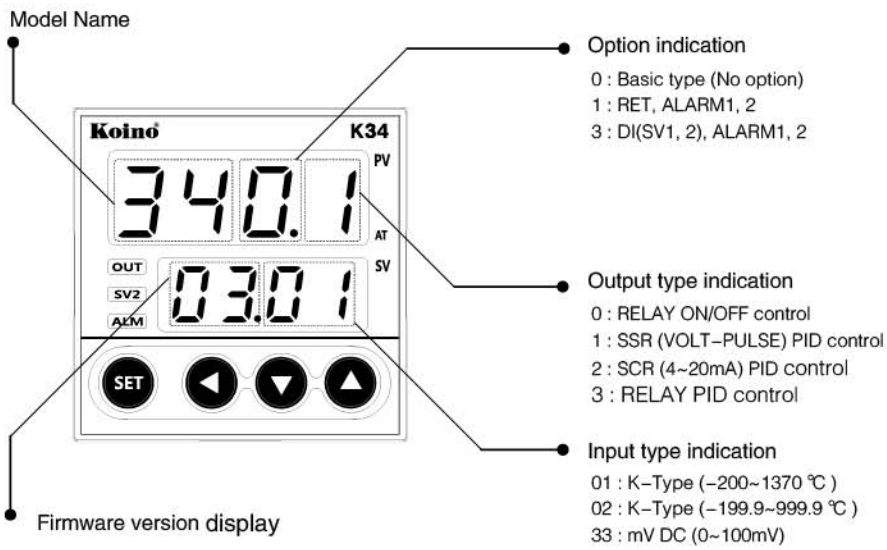
1) Default values at the point of manufacture

The default input and output values of the product at the point of manufacture are as follows.
Input : K-Type (Sel. code 1) Output : SSR mode (Sel. code 1)
※ In the case of the basic model of K34-S00 only, when SSR(1) or SCR(2) is chosen as the output mode, Alarm 1 output will be in main relay. (Refer to page 8 for details)

2) 7 Segment display indications

A	B	C	D	E	F	G	H	I	J	K	L	M
N	O	P	Q	R	S	T	U	V	W	X	Y	Z

3) Initial display on power supply (K34-SERIES basis)



8. Initial installation and minimum operation procedures

The following are the instructions for initial installation and minimum operation procedures.
Please read the contents of this manual, including the general functions outlined here, as thoroughly as possible before operating the device.

1) Check the external wiring diagram and specifications
(power supply and terminal arrangement)
2) Check input and output specifications!
The default setting for the K30 series at the point of manufacturer are as follows.
Input : K(CA) Type (setting code 1)
Output : SSR mode (setting code 1)
If you wish to change the input or the output type, please select the option you desire on the input group and the output group menus.
※ The input type settings must be configured first before changes to other set values are made. When the input type is changed, all other parameters (set values) are reverted to their factory default.
3) Select the desired set value (SV).
4) Please set auto-tuning or P, I, D values to suit the operating environment.
Auto-tuning is recommended except under special circumstances

Set value(SV) setting [in condition of Mvn = OFF (basic)]

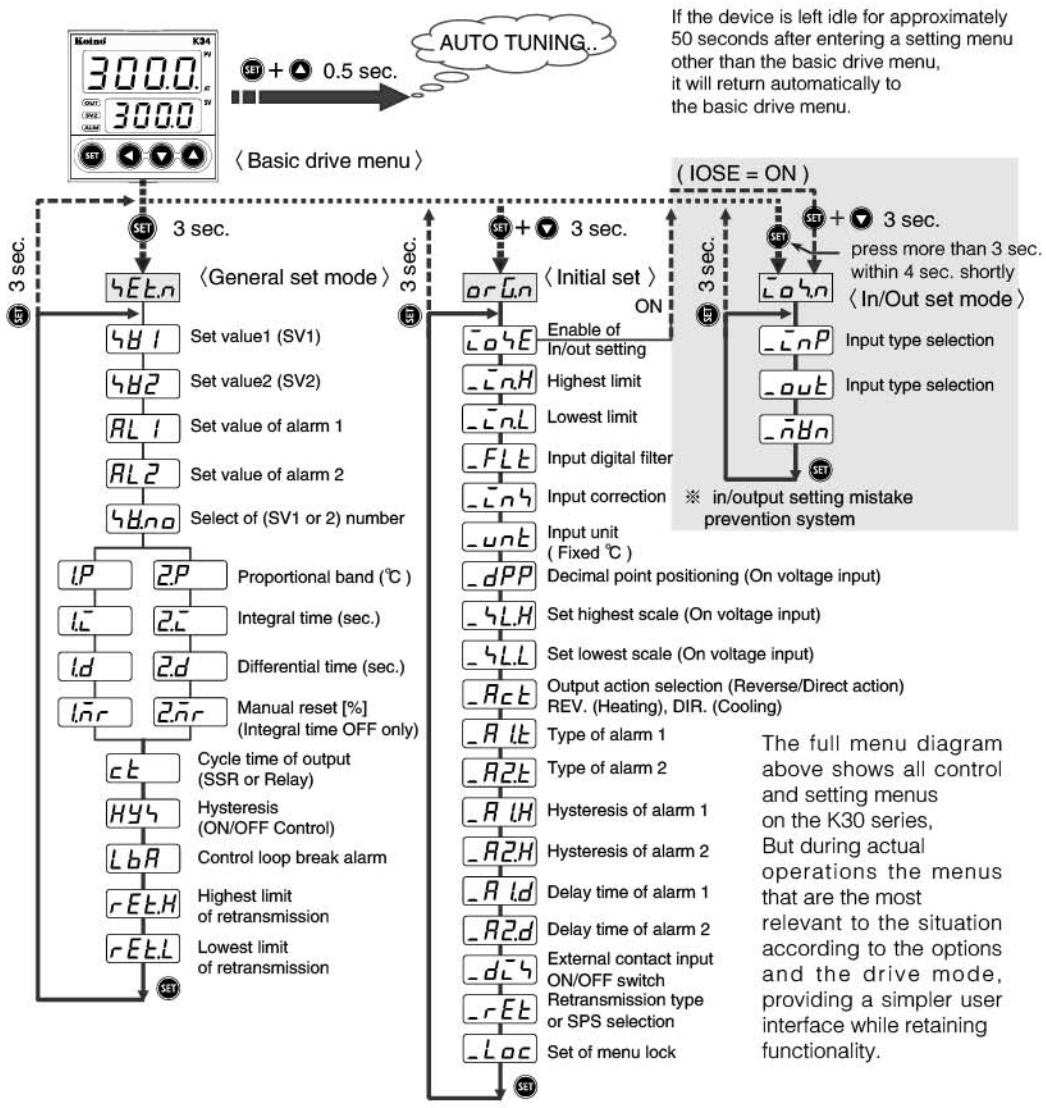
① Enter to setting mode by SET key
② Set a desired value by ◀ ▼ ▲ key
③ Store a value by SET key

Auto tuning

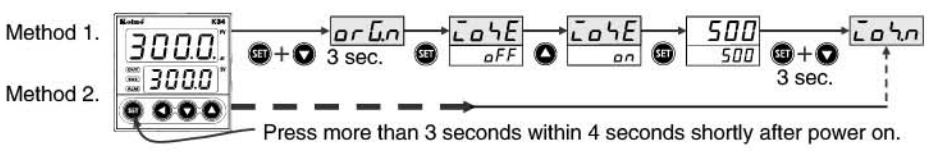
AT operation start: SET + ▲ 0.5 second
AT stop by perforce: SET + ▲ 0.5 second
AT command lamp (flash every 0.5sec.)

Tuning is required before operating for the first time. Set the target value(SV) in the range mainly used and run auto-tuning. When auto-tuning begins, the "auto-tuning command lamp" will flash every 0.5 second and will turn off upon completion of the tuning process. Please refrain from operating the keys while auto-tuning is in progress.

9. Flow Chart (Parameter structure)



〈 Process of "in/output set mode" 〉



※ To enter "Input/Output settings" by "IOSE" On is valid for only one time. If you want to enter "Input/Output settings" again you must turn on "IOSE" first. If there is no Key action the "IOSE" will be OFF automatically in 40 seconds.

10. Setting mode

1) General setting mode

The general setting mode is for changing environment parameters on ad hoc basis and also for tuning performance enhancement and configuring other functionalities.

Display	Description	Setting range	Condition	Initial value
SEt.n	Display general setting mode	—	—	—
SV 1	Set value 1 (SV1) setting	EU (0 ~ 100 %)	D.I Option in use	EU (0 %)
SV2	Set value 2 (SV2) setting	EU (0 ~ 100 %)	D.I Option in use	EU (0 %)
AL 1	Set value of alarm 1 (AL1)	EU (0 ~ 100 %)	Use Alarm 1	EU (100 %)
AL2	Set value of alarm 2 (AL2)	EU (0 ~ 100 %)	Use Alarm 2	EU (0 %)
SV.no	Selection of (SV1, 2) number	1 / 2	Always	1
n.P	SV1, 2 proportional band (P)	0 ~ 999.9 ℃	PID control	20.0 ℃
n.I	SV1,2 Integral time (I)	OFF / 1 ~ 6000 sec.	PID control	240 sec.
n.d	SV1,2 Differential time (D)	OFF / 1 ~ 6000 sec.	PID control	60 sec.
n.nr	SV1,2 Manual reset (MR)	–5.0 ~ 105.0 %	Integral time OFF	50.0 %
ct	Cycle Time (P.I.D Control Only)	1 ~ 1000 sec.	PID control (SSR or RELAY)	2 sec.
HYS	Hysteresis (ON/OFF control)	EUS (0 ~ 100 %)	ON/OFF control	EUS (0.5 %)
LbA	Control loop break alarm (LBA)	OFF / 1 ~ 9999 sec.	ALARM1 No. 21 selection	480 sec.
rEt.H	Highest limit of retransmission (RET.H)	TC/RTD : _IN.H~_IN.L DCV IN : _SL.H~_SL.L (But, RET.H > RET.L)	Use retransmission and select PV or SV	EU (100 %)
rEt.L	lowest limit of retransmission (RET.L)			EU (0 %)

※ EU : An engineering unit in compliance with the input range

ex) Input selection no. : 01 (K–TYPE)

EU 0 % = –200
EU 100 % = 1370

EUS 0 % = 0
EUS 100 % = 1570

2) Initial setting mode

The initial setting mode is for setting up initial parameters and configuration for overall control and functionalities activation that are rarely changed after the initial setup.

Display	Description	Setting range	Condition	Initial value
orG.n	Initial set mode (ORG.N)	—	—	—
CoSE	I/O setting entry switch (IOSE)	ON / OFF	Always	OFF
_InH	Set highest input range (_IN.H)	Within input range (See input type and range) But, _IN.H > _IN.L	Always	1370
_InL	Set lowest input range (_IN.L)			–200
_FLt	Set input digital filter value (_FLT)	OFF / 1~120 sec.	Always	OFF
_Ins	Input value correction (_INS)	OFF / 1~120 sec.	Always	OFF
_unt	Input temperature unit selection (Fixed Celsius)	℃ / ℉	TC or RTD input	℃
_dPP	Select the decimal point position in Voltage input mode (_DPP)	0 ~ 3	Voltage or 4~20mA input mode only	1
_SLH	Free scale upper limit set (voltage input mode)	–1999 ~ 9999 But , SL–H > SL–L Decimal point positioning by _DPP		100.0
_SLL	Free scale lower limit set (voltage input mode)			0.0
_Act	Output action selection	REV (Heating), DIR (Cooling)	Always	REV (Heating)
_A1t	Select alarm 1 output type	OFF / 1 ~ 21(LBA) (See alarm type)	Always	1
_A2t	Select alarm 1 output type	OFF / 1 ~ 20 (See alarm type)	Using alarm 1, 2 option	2
_A1H	Hysteresis of alarm 1 output	EUS (0.0 ~ 100.0 %)	Using alarm1 (1~20)	EUS (0.5%)
_A2H	Hysteresis of alarm 2 output	EUS (0.0 ~ 100.0 %)	Using alarm2	EUS (0.5%)
_A1d	Delay time of alarm 1	OFF / 1 ~ 240 sec.	Using alarm1	OFF
_A2d	Delay time of alarm 2	OFF / 1 ~ 240 sec.	Using alarm2	OFF
_dIn	External contact input (SV1, 2) ON/OFF switch	OFF / ON	Using RET option	OFF
_rEt	Retransmission type or SPS selection	PV / SV / MV / SPS	Using RET option	PV
_Loc	Set data protection	OFF / ON / ALL	Always	OFF

2) In/Output setting mode

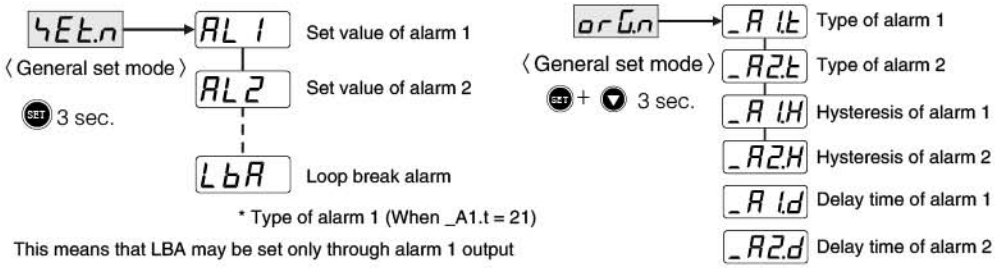
The input/output setting mode is a parameter for the first time use. It' s a hardware configuration so requires special user caution. That is, the configuration is determined by the type of equipment and it must be configured first. (※ all parameters are initialized according to the entered input type)

Display	Description	Setting range	Condition	Initial value
in.o	In/output setting mode	—	—	—
_inP	Input type selection (_InP)	1 ~ 33 (refer to P7, 2–1.)	Always	1
_out	Output type selection (_out)	0 ~ 3 (refer to P8, 2–2.)	Always	1
_Mvn	Manipulated variable (_Mvn) Display setting	OFF / ON	Always	OFF

When the input type is changed, all parameters are reverted to their factory default. This means that before using the K30, the input type needs to be set first, after which other parameters can be configured. If the input settings are changed while in use, auto–tuning and other parameters need to be reconfigured.

10. Setting mode

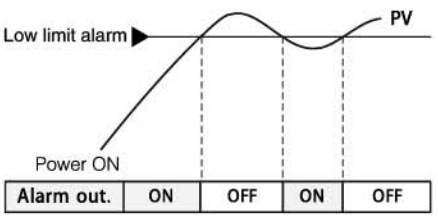
The K30 series has two separate alarm outputs, and in the setting group, alarms may be chosen among 21 types, and the dead band (hysteresis) for the alarm output may be set.
Please find the alarm code with the desired function in the "Alarm types and codes table" on the next page and use it to set the alarm output type in the settings mode.



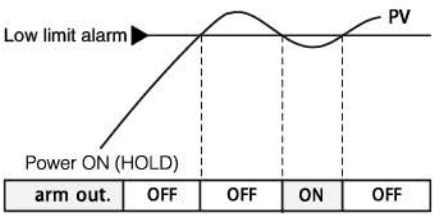
1) Hold function

When a low alarm is set and during temperature is rising, an unnecessary low alarm may be happen. The hold function may be used to eliminate such problems.
The hold function allows the low alarm to be ignored automatically until the temperature rises above the alarm threshold level for the first time when electricity is first turned on.

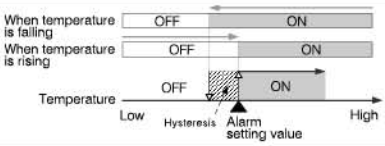
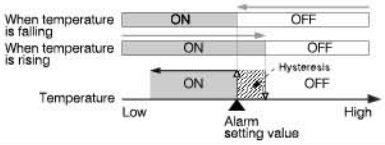
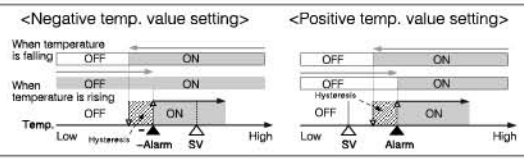
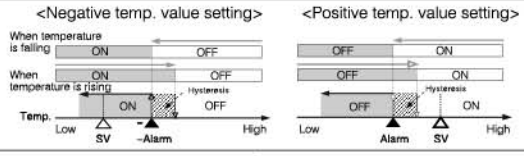
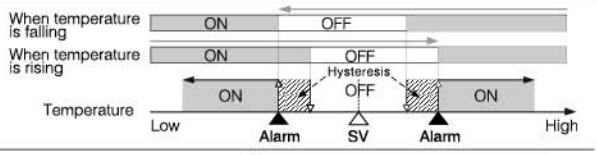
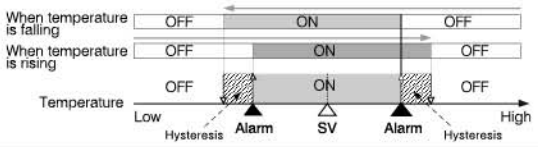
Hold function: None



Hold function

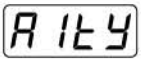


2) Alarm output type and Selection code

Code no.	Alarm type	Alarm output operation
01	Absolute value upper-limit	
09	(Inverted output)	
11	with Hold function	
19	with hold function (Inverted)	
02	Absolute value lower-limit	
10	(Inverted output)	
12	with Hold function	
20	with hold function (Inverted)	
03	Upper-limit deviation	
05	(Inverted output)	
13	with hold function	
15	with hold function (Inverted)	
04	Lower-limit deviation	
06	(Inverted output)	
14	with hold function	
16	with hold function (Inverted)	
07	Upper & Lower-limit deviation	
17	Upper & Lower-limit deviation with hold	
08	Upper & Lower-limit deviation in range	
18	Upper & Lower-limit deviation in range with hold	
21	Loop break alarm (LBA)	Refer to HBA ! (ALARM1 only)

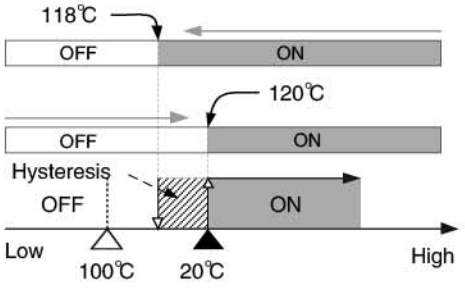
When alarm type reverse-correspondence is selected for alarm type and code, please be aware that when the alarm lamp turns on, the contact output will be off.

Example of Alarm output 1 setting


Alarm type (Upper-limit deviation) = 03


Hysteresis (Dead band) = 2 ℃


Alarm setting value = 20 ℃



(When Set value (SV) = 100 ℃)

12. Details explanation of primary function

12–1. Auto tuning (AT) function

Before the PID temperature controller can be used for the first time, the P, I, D values must be tuned. The auto–tuning function finds the optimal value by tuning automatically according to the load factor and other conditions.

Please make sure that the controller is tuned before using it for the first time, by defining the set values in the most frequently used range and running auto–tuning. When auto–tuning begins, the "auto–tuning command lamp" will flash every 0.5 second and will turn off upon completion of the tuning process. Please refrain from operating the keys while auto–tuning is in progress.

AT operation start : (SET) + (▲) 0.5 second

AT stop by perforce: (SET) + (▲) 0.5 second

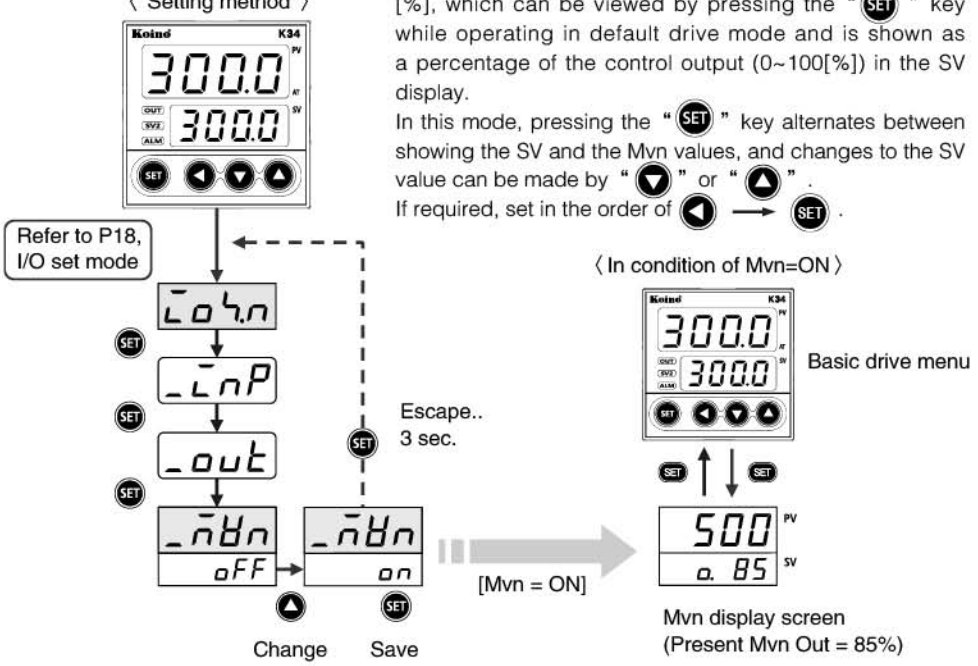
AT command lamp (flash every 0.5sec.)

※ Do not use auto tuning under below Process.

- Rapid control Process such as Flow, input control.
- Process which should not ON/OFF output even a temporary.
- Process which should not over load at control.

12–2. Manipulated Variable [%] (Mvn) check mode

〈 Setting method 〉



"Mvn [%] check function" displays the control output [%], which can be viewed by pressing the " (SET) " key while operating in default drive mode and is shown as a percentage of the control output (0~100[%]) in the SV display.

In this mode, pressing the " (SET) " key alternates between showing the SV and the Mvn values, and changes to the SV value can be made by " (▼) " or " (▲) ".

If required, set in the order of (◀) → (SET).

12-3. Alarm (ALARM1,2) function

The K30 series has two separate alarm outputs, and in the setting menu, alarms may be chosen among 21 types, and the hysteresis, delay time for the alarm output may be set. Please find the alarm code with the desired function in the "Alarm types and codes table" on the page 21~22 and use it to set the alarm

【1】 Delay time of alarm

Alarm 1 delay time setting

Alarm 2 delay time setting

If you set the alarm delay time, alarm (1 or 2) output waits for the delay time after receiving the alarm. However, it is not applicable when the alarm is turns off.
During the delay time the alarm (ALM) output lamp blink 0.5 second intervals to displays the current alarm is waiting to alert.

【2】 LBA (Control Loop Break Alarm)

LBA is functionality where it triggers an alarm when there is no change in input while the difference is in consistent state (it assumes there is certain problem in the control loop). Therefore if the control loop is not in a normal working mode, it can be utilized for detection. E.g. output is generated if there are problems with control unit and other problems or can be used for heater disconnection.

How to set up

Please set value of LBA two times of the normal integral time setting.
In addition, LBA can be set to automatically by the auto turning function.
In this case value will be set up automatically two times of integral times.

Description of operation

Control loop break alarm consists to alert you Control loop break by detect Variation during setting time when P.I.D calculations (On time/period of output) is 0% or 100%.

① When P.I.D calculations stays 100% more than LBA setting time, Break alarm will be turned on if calculations is not increase more than 2℃
(In positive action will turned on if calculations does not fall more than 2 ℃)
② When P.I.D calculations stays 0% more than LBA setting time, Break alarm will be turned on if calculations is not fall more than 2℃
(In positive action it will turned on if calculations does not increasemore than 2 ℃)

Cause of activation

LBA will activate below condition.

1) Abnormalities of the control target : Heater break, No supply voltage,Wrong wiring .etc

2) Abnormalities of the sensor : Disconnection / short circuit of sensor
3) Abnormalities of the handling tools : Splice relay, wrong wiring. etc
4) Abnormalities of Output circuit : Spliced relay inside of unit, break ON/OFF
5) Abnormalities of input circuit : No calculations change even input is change.

Notice

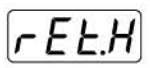
1) LBA will work when PID calculations is 0% or 100%. Thus the time from occurring of abnormalities to alarm time will be the time of PID value 0% or 100% plus
2) LBA set-up times LBA will not working during auto tuning.
3) The LBA function is influenced by disturbances (heat sources, etc) and as a result may be activated even if there is no trouble in the controlled system.
4) When LBA setting time is too short or wrong control target, sometimes LBA will be on/off abnormally of not turned on. In this case please set LBA time little longer.

12-4. Retransmission output

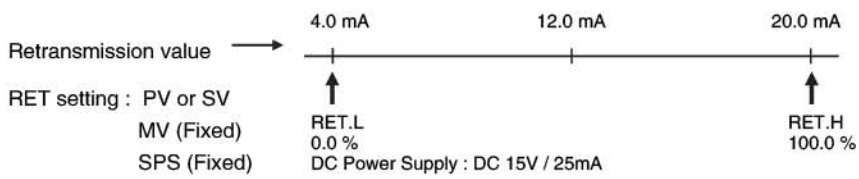
In the retransmission output mode, process value (PV), set value (SV), output amount (MV), or sensor power supply (SPS) may be chosen, and the output will be generated in direct current of 4~20mA. (SPS is DC15V/25mA)

Retransmission type or SPS selection

PV (Current Progress Value)
SV (Set Value)
MV (Manipulated Variable)
SPS (Power supply for external sensor)



Scale setting can only possible when retransfer output set-up PV or SV.



12-4. Retransmission output

1) Digital input filter (_FLT)

This function is useful when suboptimal environments cause noises or severe fluctuations, enabling a digital software filter. The filter' s sensitivity may be set from off to 1~120 seconds. Please be careful when using this function, as it may affect the control-related algorithms.

2) Input value correction (_INS)

This function allows the input values to be compensated. This function is useful, for example, when sensors cannot be placed at desired locations, or when several different thermometers are used in conjunction. The values may be compensated to extent desired by the user.

3) Setting decimal point position (_DPP),
and free scale high and low limits (SL–H, SL–L)

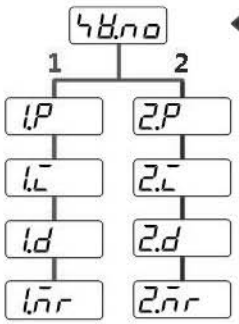
This applies only when using voltage inputs (DC V, mV) or currents between 4 to 20mA (1~5V).
The user may set ranges, units and decimal point position as desired.
This can be used not only for temperatures but also for a number of other measurements, including humidity, pressure, and weight.

12–6. SV1, 2 set up control by External contact signal

_dC4	Use SV1,2 by external contact (_diS=ON)	
	SV Action	External terminal status
ON	SV1 Select	OPEN
	SV2 Select	SHORT
OFF	Block external contact signal (Can select under inside menu only)	

Digital input switch (_DIS) :
This function selects whether to use digital input switch. This function the ability to change SV1, 2 to Each pre–set value by an external contact signal.

Please use a non–voltage contact (relays, switches) for direct input. If a non–contact device such as a semiconductor are used, please operate within the ranges ON = under 1KΩ, OFF = over 100KΩ.



"SV1,2" selection menu when the (_diS = OFF).

K30 controls when the external or internal SV1 or SV2 select control by independent P, I, D, MR value. As a result, it will have best control performance depending on the temperature value. Typically, when use Auto–tuning, it will work if either SV1 or SV2 tuned and set same P, I, D value with the other.

12–7. Set value "LOCK" function

Lock function will protect change set value and activate function such as auto–tuning from accidental key operation. Please use after setting prevents.

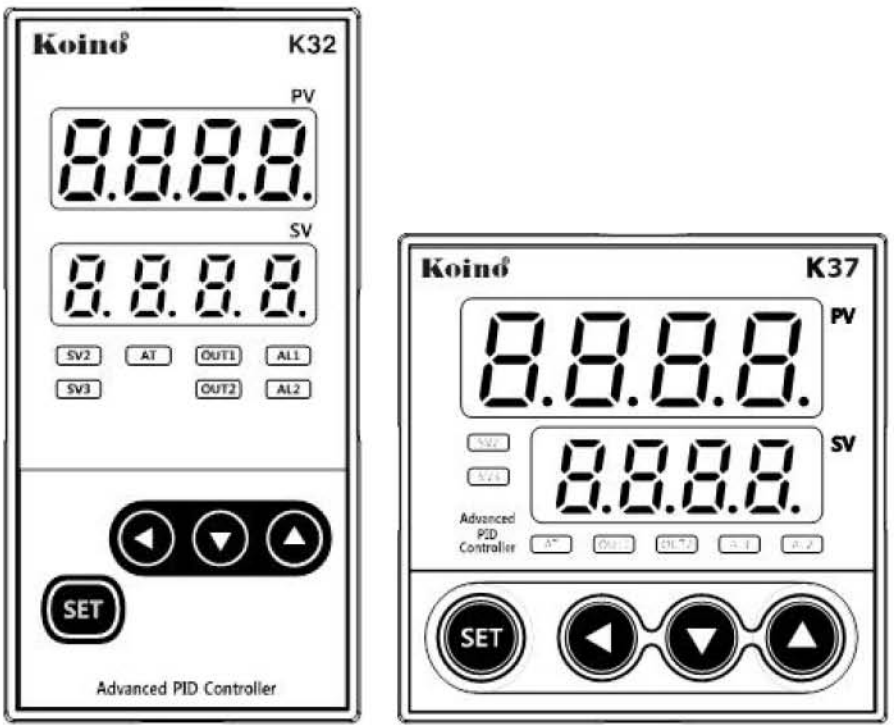
Lock has 3 setting mode (OFF / ON / ALL)

- OFF : LOCK function off
- ON : Can operate SV setting and AT only.
- ALL : Impossible all setting and operation, only LOCK OF is available.

MICRO COMPUTER

Digital PID Controller
User' s Manual

K50–SERIES



Koino®

Preface

Thank you for purchasing the K50 series from Koino.
The K50 series is a precision industrial controller that uses an advanced 2 degree-of-freedom (DOF) algorithm.
The K50 series consists of 5 models, which are K52, K53, K54, K57, and K59.
This manual explains the installation, the functions, the operation, and the handling of the products.
Please read the manual thoroughly before using the products.
If any difficulties arise while using our products, please call our customer service at 82-2-2242-1275.

Pay attention to the followings!

- Use the products under the conditions specified in this manual.
- Please heed the cautions and warnings listed in this manual.
- The contents of the manual may be changed without notice.
- The product is designed to be used installed on a control panel.
- This manual is copyrighted, and may not be copied in part or in whole without permission.
- The manufacturer takes no responsibility for direct or indirect damages caused by careless operation or operation under unpredictable or risky environments.

Safety requirements!

Safety requirements are intended to prevent accidents and dangers through the proper use of the products, so please heed them at all times.
The safety requirements are divided into **"cautions"** and **"warnings"**, which indicate the following.

⚠ WARNING

Serious injury or death may be caused if instructions are not observed.

⚠ CAUTION

Failure to observe these instructions may cause damage to the instrument or some injury to the user.

⚠ WARNING

1. Use a separate safety device when this product is used to control a device that could harm lives or expensive property in the event of a malfunction or a breakdown. (This may cause fires, deaths, or damage to property)
2. Do not use this controller at place where there are flammable or explosive gas. (It may cause a fire or explosion.)
3. Before turning the power on, please check that wiring is correct to the number of terminal. (It may cause a fire)
4. Turn off the power during wiring and maintenance to avoid an electric shock.
5. Do not touch the terminals when it is power on. (It may give an electric shock.)
6. This controller must be mounted on the panel to avoid an electric shock.
7. Do not attempt to disassemble, modify and repair.

⚠ CAUTION

1. Please conduct an inspection when water has entered the product. (It may cause short circuits, fires, and malfunction.)
2. This controller should be used indoors. (It may shorten the controller' s life or give an electric shock.)
3. Observe the rated voltage and specification. (It may cause a fire or shorten the controller' s life.)
4. Be careful that any of foreign materials do not inflow into the controller. (It may cause a fire or malfunction of the controller.)
5. Do not give direct vibration or shock to the controller. (It may cause of malfunction of the controller.)
6. Do not use chemical detergent or solvent, but use a dry towel in cleaning the controller. (It may cause an electric shock or a fire.)
7. Please check the polarity of power before wiring and connecting the sensor. (It may cause an electric shock or explosion.)

Contents

K5 □ – □ □ □

④ Power supply voltage
③ Optional function
② Control mode
① Size

① Size

Code	Model	Size	Remarks
2	K52–SERIES	48(W) × 96(H) × 77(D)	Option : 0, 1, 2
3	K53–SERIES	96(W) × 48(H) × 77(D)	Option : 0, 1, 2
4	K54–SERIES	48(W) × 48(H) ×99(D)	Option : 0, 1, 2, 3, 4, 5, 6
7	K57–SERIES	72(W) × 72(H) × 77(D)	Option : 0, 1, 2
9	K59–SERIES	96(W) × 96(H) ×77(D)	Option : 0, 1

② Control mode

Code	Description	Remarks
S	SINGLE : Standard	Heating or Cooling control
D	DUAL : Heating & Cooling	Heating and Cooling control

④ Power supply voltage

Code	Description	Remarks
0	100 ~ 240 V AC	General–purpose usage
1	24 V AC or DC	Alternating or Direct current usage

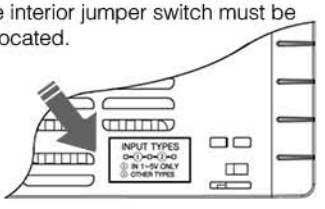
③ Optional function

Model	Code	Description	Remarks
K52, K53	Basic function	RELAY output 1, Alarm output 2, SCR(4~20mA), SSR(Voltage pulse) 1, RET(4~20mA Retransmission output)	Basic function + (Option code)
	0	D.I (SV2, 3) External digital input	Ex) K52, K53-S00
	1	Communication (RS-485, Modbus)	Ex) K52, K53-S10
	2	HBA(CT) Heater break alarm	Ex) K52, K53-S20
K54 SERIES	Basic function 0	RELAY output 1 (ALARM or MAIN), SCR(4~20mA), SSR(Voltage pulse) 1	Basic function + Option code (0 : No option)
	1	RET(4~20mA Retransmission), Alarm 2	Ex) K54-S10
	2	HBA(Heater break alarm), Alarm output 2	Ex) K54-S20
	3	D.I(SV2, 3) External input, Alarm output 2	Ex) K54-S30
	4	RET(4~20mA Retransmission), Communication (RS-485, Modbus)	Ex) K54-S40
	5	HBA(CT) Heater break alarm, Communication (RS-485, Modbus)	Ex) K54-S50
	6	D.I(SV2, 3) External input, Communication (RS-485, Modbus	Ex) K54-S60
K57 SERIES	Basic function 0	RELAY output 1, Alarm output 2, SCR(4~20mA), SSR(Voltage pulse) 1	Basic function + Option code (0 : No option)
	1	Communication (RS-485, Modbus), RET(4~20mA Retransmission), HBA(CT) Heater break alarm	Ex) K57-S10
	2	D.I(SV2, 3), RET(4~20mA Retransmission), HBA(CT) Heater break alarm	Ex) K57-S20
K59 SERIES	Basic function 0	RELAY output 1, Alarm output 2, SCR(4~20mA), SSR(Voltage pulse) 1, RET(4~20mA Retransmission)	Basic function + Option code (0 : No option)
	1	Communication (RS-485, Modbus), HBA(CT) Heater break alarm	Ex) K59-S10

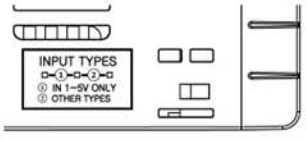
2. Input ranges and output constitutions

2–1. Input ranges

※ The K50 series has multiple inputs, which may be set and changed by the user.

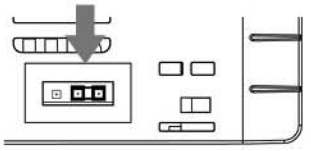
Input type	Signal	Setting Code	Temperature range	Accuracy	Remarks
Thermocouple (T.C)	K	1	–200 ~ 1370	± 0.3% of F.S +1Digit	* F.S is max. value to min. value of each range * Digit is minimum of display ① 0~400℃ range : ± 10% of F.S+1Digit
		2	–199.9 ~ 999.9		
	J	15	–200 ~ 1000		
		3	–199.9 ~ 999.9		
	E	16	–200 ~ 1000		
		4	199.9 ~ 999.9		
	T	5	–199.9 ~ 400.0		
	R	6	0 ~ 1700		
	B ①	7	0 ~ 1800		
	S	8	0 ~ 1700		
	L	17	–200 ~ 900		
		9	–199.9 ~ 900.0		
	N	10	–200 ~ 1300		
	U	11	–199.9 ~ 400.0		
	C (W5)	12	0 ~ 2300		
	D (W3)	13	0 ~ 2400		
RTD	JPt100 Ω (JIS,KS)	20	–199.9 ~ 500.0		
		22	–200 ~ 500		
	Pt100 Ω (DIN,IEC)	21	–199.9 ~ 640.0		
		23	–200 ~ 640		
Voltage (VDC/mVDC)	0~100 mV DC	33	0 ~ 100mV DC		
	–10~20 mV DC	32	–10 ~ 20 mV DC		
	1~5V DC	30	1~5V DC	※ When using 1~5V input (30), the interior jumper switch must be relocated. 	
Current	4~20mA DC	30	When using current input, use the resistor 250Ω on input terminal.		

How to change the interior switch when using 1~5V input



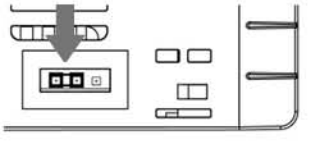
① Remove the jumper cover on the underside of the T50, or remove the rear case.

OTHER TYPES



② Detach the jumper using tweezers and move it to the 1–2 pins to the left.

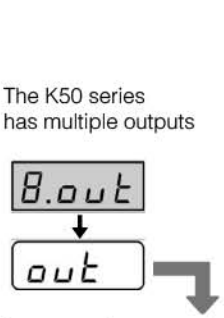
1~5V DC INPUT ONLY

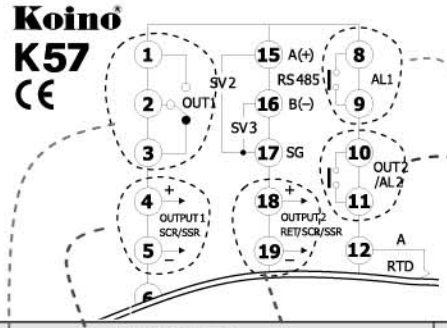


③ Once this has been com–pleted, put the jumper cover back on, as shown on the picture above.

2–2. Output constitutions

The K50 series has multiple outputs





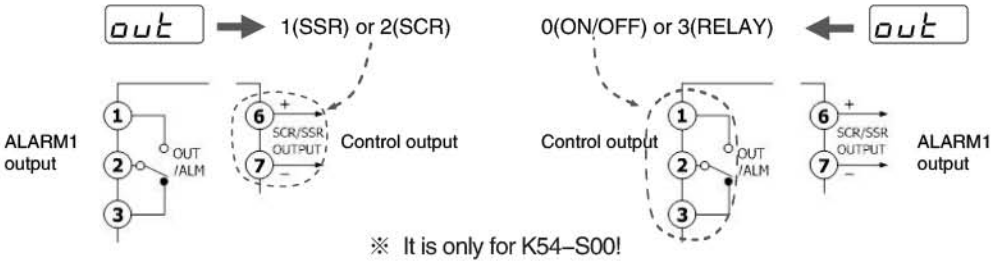
※ The figure on the left uses the terminal socket of K57–S20 as an example to illustrate the output response relationship. relationship.

General type	Setting number	OUTPUT–1			OUTPUT–2 (ALARM1,2)		
		Relay output	SSR/SCR OUTPUT		AL1	AL2	SCR output
			SSR output	SCR output			
K50–Sxx	0	OUT(ON/OFF)	OUT(ON/OFF)	–	ALARM1	ALARM2	RET
	1	ALM1(54–S0x)	ALM1(54–S0x)	–			
	2	ALM1(54–S0x)	ALM1(54–S0x)	OUT(PID)			
	3	OUT(PID)	OUT(PID)	–			

Summary and explanation of output settings

- Relay output of ON/OFF control [Output setting number : 0]
  This is a simple on/off control, mainly used to control cooling devices.
- SSR output of PID control (Voltage pulse) [Output setting number : 1]
  This is the most widely used setting, and the default value at the point of manufacture.
- SCR output of PID control (4~20mA current output) [Output setting number : 2]
  This setting is used mainly with thyristor power regulator (TPR) modules, and is capable of precision control.
- Relay output of PID control [Output setting number : 3]
  This is the most cost–efficient method of implementing PID control and is used mainly with magnetic switches (electric switches). However, it may wear the contact point, and is difficult to use in places that require fast response.

Alarm output of K54(48 × 48) basic type(S00)

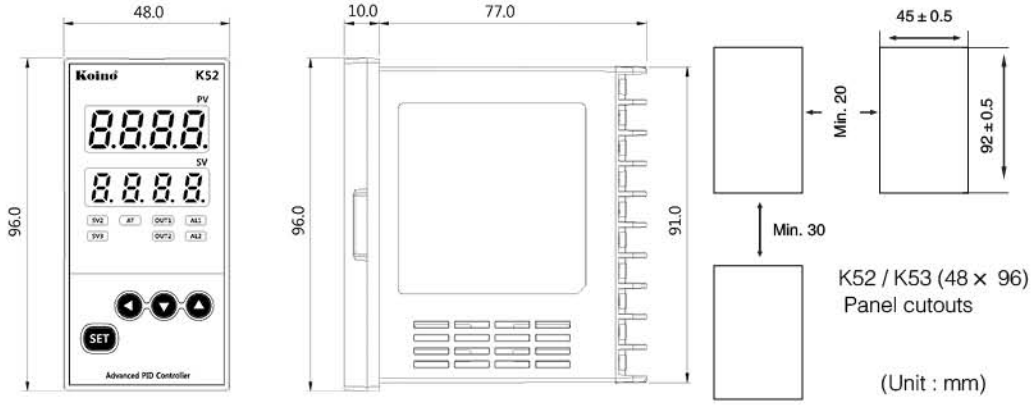


※ It is only for K54–S00!

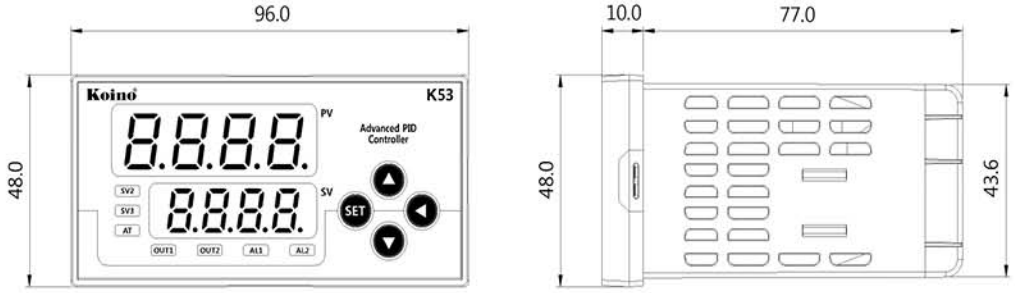
With the basic model of K54 (48x48), caution is required when using it alarm output. When control output is being used as a relay, the alarm output will be SSR output (voltage pulse). In this case, use SSR or alarm option (S10, S20, S30) enabled models.

3. Dimensions and panel cutouts

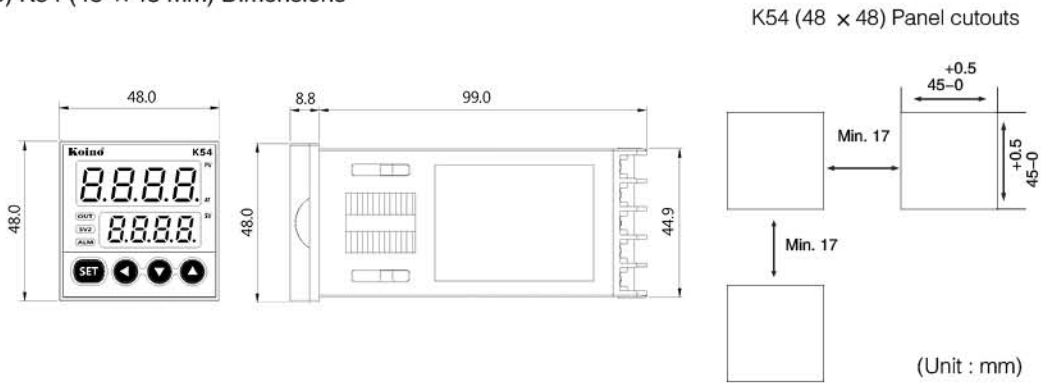
1) K52 (48 × 96 mm) Dimensions



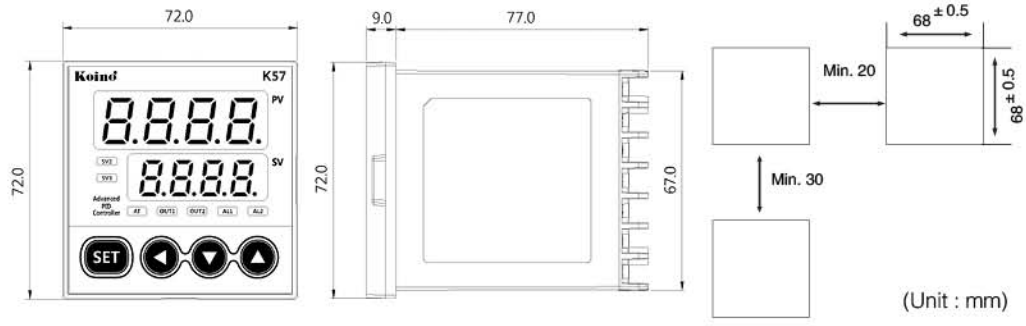
2) 2) K53 (96 × 48 mm) Dimensions



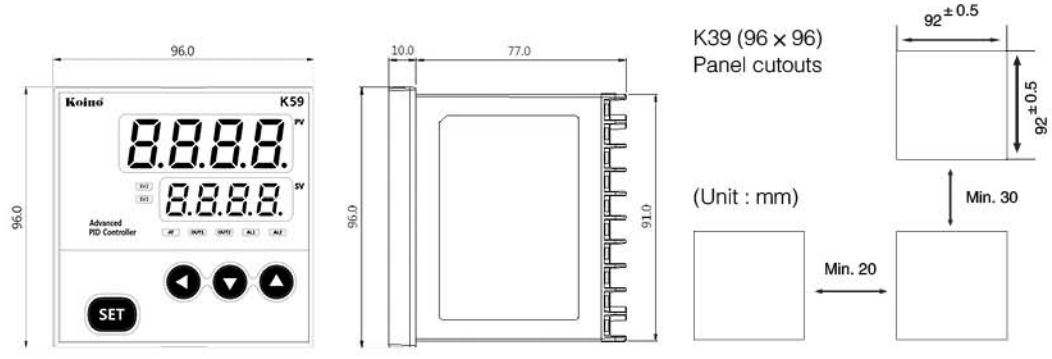
3) K54 (48 × 48 mm) Dimensions



4) K57 (72 × 72 mm) Dimensions

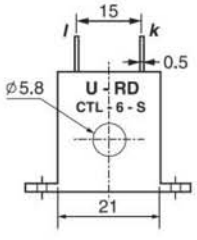


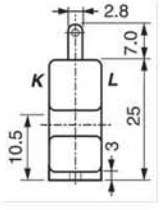
5) K59 (96 × 96 mm) Dimensions



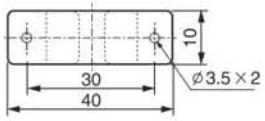
HBA option (Heater break alarm)

Current transformer (CT) : CTL-6-S or 800:1 CT use





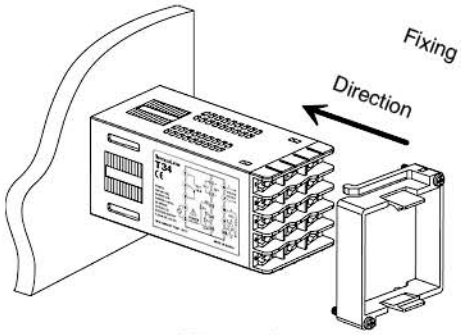
Panel cutouts



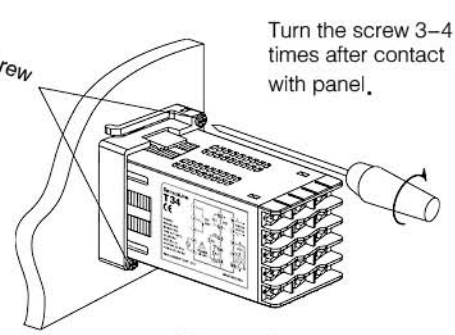
Installation

■ K54–SERIES

① Bore a hole in the panel, referring to the panel cutouts on the previous page.
② Insert this device into the front of the panel.
③ From the rear of controller, slide the bracket over the housing.
④ Push the bracket in until the device has been fixed securely onto the panel.
⑤ Secure using screws on the two locations at top and bottom as shown on Figure 2.



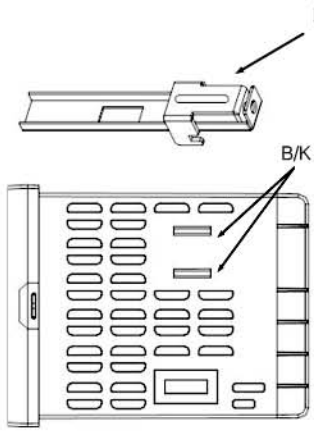
[Picture 1]



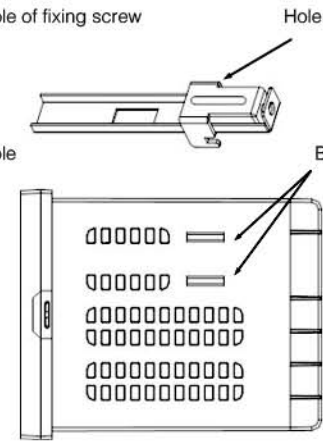
[Picture 2]

■ K52 / K53 / K57 / K59–SERIES

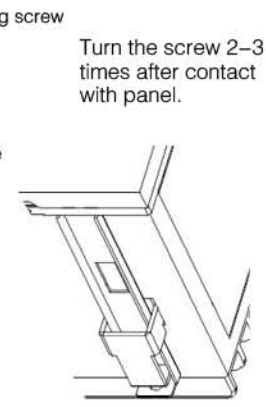
① Bore a hole in the panel, referring to the panel cutouts on the previous page.
② Insert this device into the front of the panel.
③ Insert 2 brackets, one each on the B/K holes on the top and the bottom of the device.
④ Secure using screws on the two locations at top and bottom.



[Picture 1] Top side



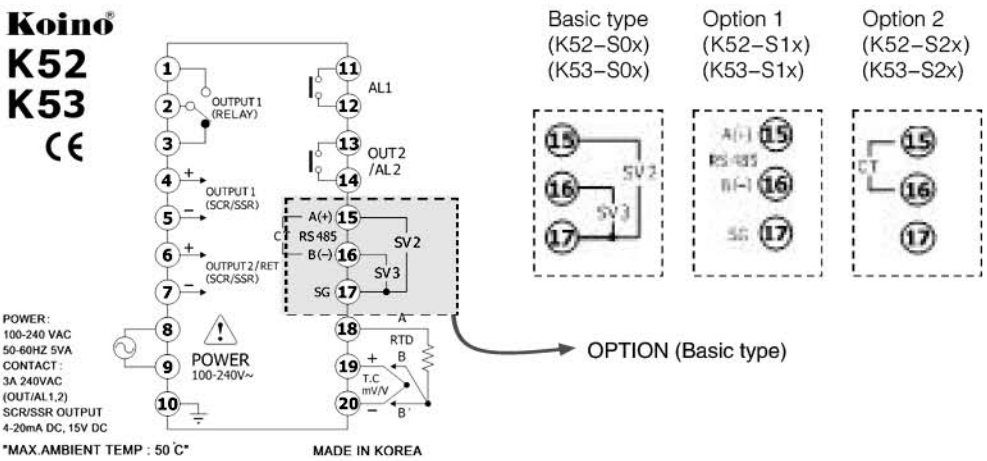
[Picture 2] Bottom side



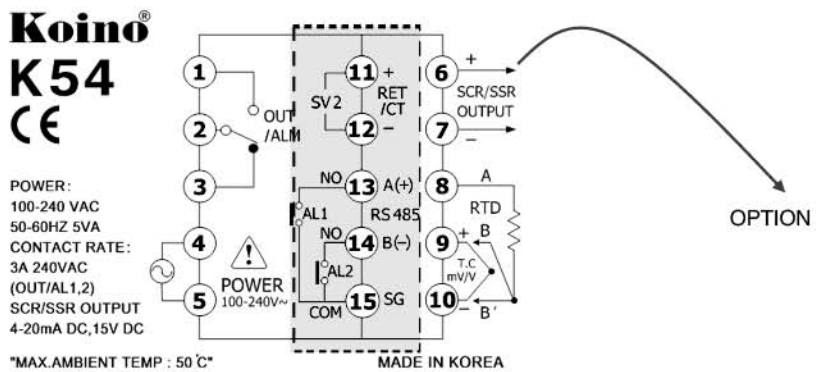
[Picture 3] Fixing completion

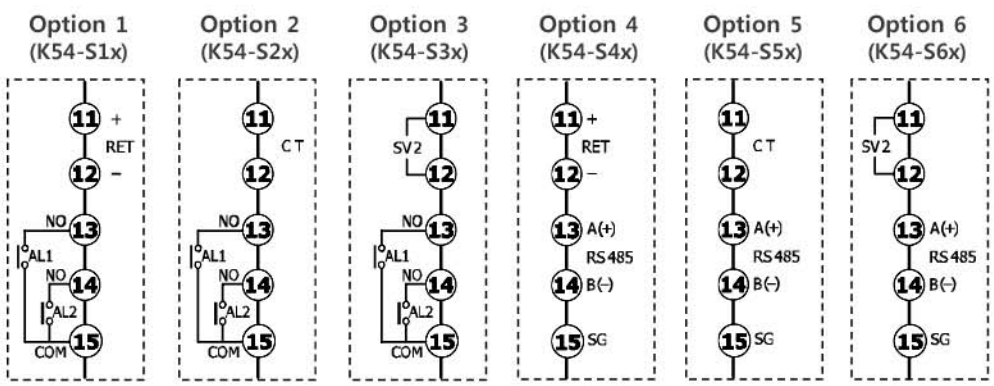
4. Terminal arrangements and wirings

1) K52 (48 × 96 mm), K53 (96 × 48 mm)

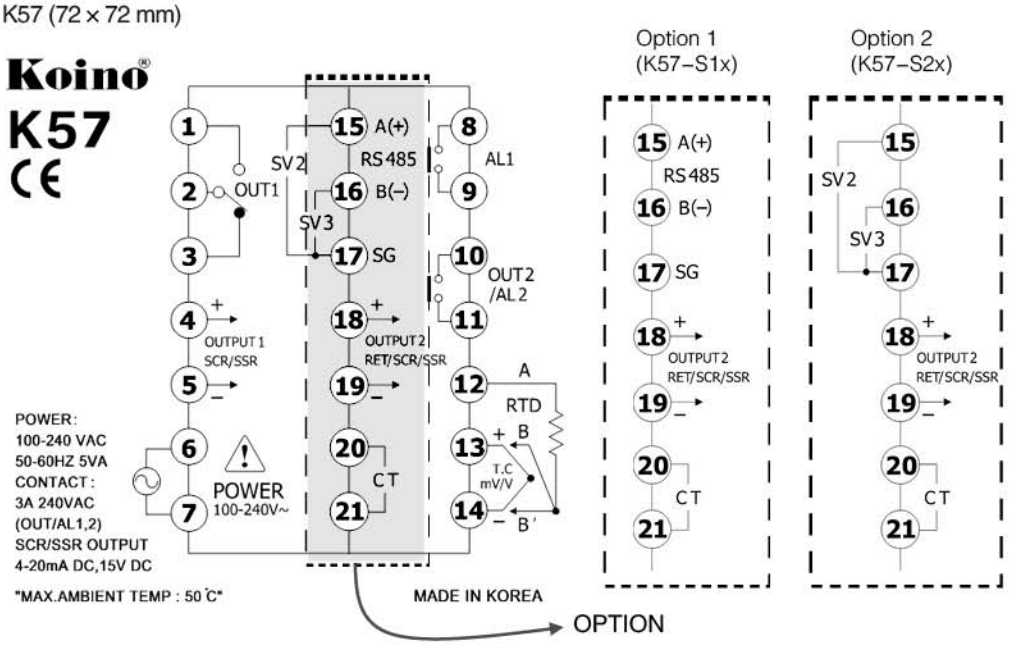


2) K54 (48 × 48 mm)

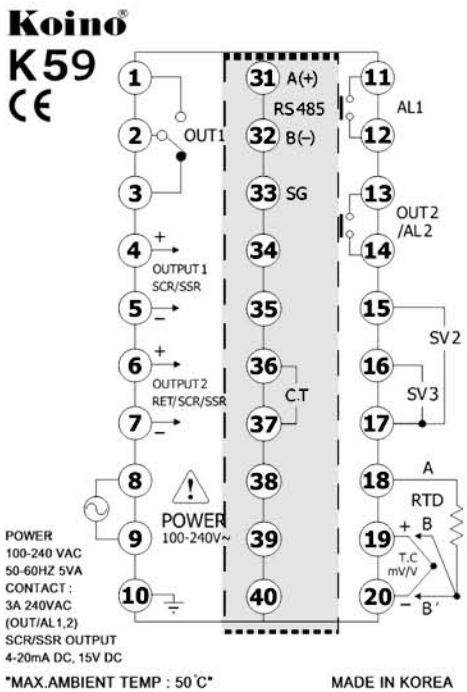




3) K57 (72 x 72 mm)



4) K59 (96 x 96 mm)



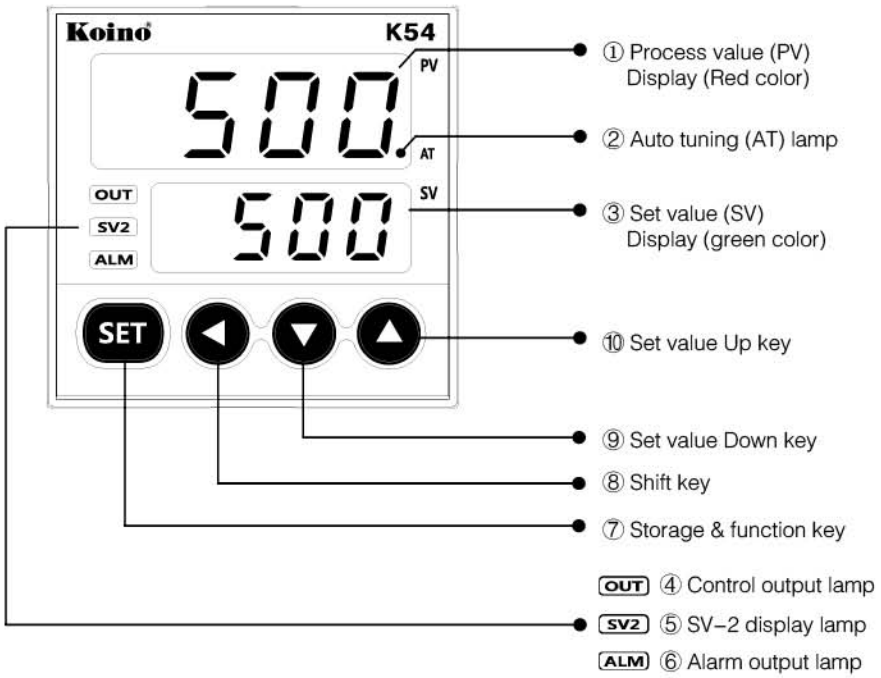
Terminal explanation (K59–S10 basis)

- Terminal (1)–(2)–(3) : OUT1 only for output selection no. 0, 3 (Relay output) mode.
- Terminal (4)–(5) : OUT2 only for output. selection no. 1, 2 (SSR, SCR output) mode.
- Terminal (6)–(7) : RET(Retransmission 4~20mA or for power of sensor SPS. (DC 15V)
- Terminal (8)–(9) : Power supply terminal.
- Terminal (11)–(12) : Alarm1 output terminal.
- Terminal (13)–(14) : Alarm2 output terminal.
- Terminal (15)–(16)–(17) : The external D.I input terminal may be used when (DIS=ON), and the target value may be controlled. (SV1, SV2, SV3)
- Terminal (18)–(19)–(20) : Input terminals.
- Terminal (31)–(32)–(33) : RS–485 communication terminals cmpletely isolated, Modbus–ASCII, Modbus–RTU, PC–Link, TL–Link basic.
- Terminal (36)–(37) : C.T(800:1) input terminals for Heater break alarm.

5. Ratings and specifications

Model		K50-SERIES
Power supply		100~240V AC 50~60Hz (Operating voltage range 85~265V AC) 24V AC or DC (Operating voltage range 20~28V DC)
Power consumption		6VA (Max.)
Sensor input		Thermocouple (TC) : K, J, T, E, R, B, S, L, N, U, C(W5), D(W3) Resistance temp. detector (RTD) : KPt100(KS), JPt100(JIS), Pt100(DIN) Current input : 4~20mA DC Voltage input : 1~5V DC, -10~20mV DC, 0~100mV DC
Accuracy		±0.3% of FS +1Digit
Input impedance		Current input (250Ω), Voltage input (including TC) 1MΩ min. (RTD allowable wiring resistance : 10Ω max., but, 3 wires have a equal resistance)
Input sampling period		250ms (changeable according to SG-PID algorithm)
Control output	Relay	1c 250VAC, 3A(resistive load) Electrical life 100,000 min. (PID output or ON/OFF output)
	Voltage (S.S.R)	DC15V 25mA (Built-in short protection circuit) Voltage pulse (PID output)
	Current (S.C.R)	4~20mA DC, allowable load impedance 600Ω max. (PID output)
Control type		Super 2 degree-of-freedom PID (SG-PID algorithm), S-Fuzzy, Auto-Tuning
Digital Input		ON : 1KΩ max., OFF : 100KΩ min. (SV1, 2, 3 external control input)
Retransmission output		4~20mA DC, allowable load impedance 600Ω or less. Resolution 1/4600 PV, SV, MV[%], SPS
Alarm	ALARM1, 2	1a 250V AC 3A (Resistive load)
	HBA(C.T) com.	HBA : 1~50A AC (Resolution 0.5A)
Communication output		2 wires RS485 totally independent insulated / Max. speed : 9,600bps Max. connect no. 99 devices (32 devices recommended) Support protocol : PC-Link, TL-Link, Modbus-ASCII, Modbus-RTU
Ambient temperature and humidity		-10~50℃ / 25~85% RH (with no condensation or icing)
Weight (incl. B/K & accessories)		● K52, K53, K57-SERIES : 230g ● K54 : 140g ● K59 : 320g ※ When option + 30g

6. Name & Function (ex. K34–SERIES)



◆ Description

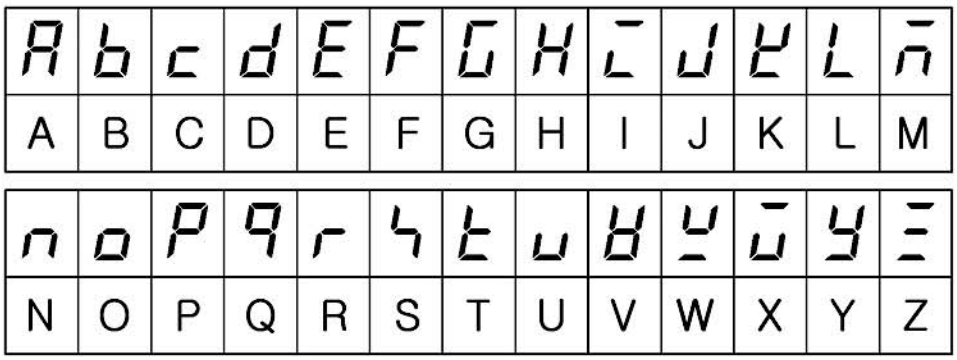
Name	Function
① Process value	Display the process value. (red color)
② Auto tuning lamp	Flash every 0.5 second during auto tuning.
③ Set value display	Display the set value, codes, and modes.
④ Control output lamp	Lights when the control output is ON.
⑤ SV–2 display lamp	Lights when the SV 2 is displayed.
⑥ Alarm output lamp	Lights during the alarm is ON.
⑦ SET Function key	Use to move the menus, to store, and to operate.
⑧ ◀ Shift key	Use to shift the digits.
⑨ ▼ Set value down key	Use to decrease set value and to move the menu.
⑩ ▲ Set value up key	Use to increase set value and to move the menu.

7. Check Points before Using

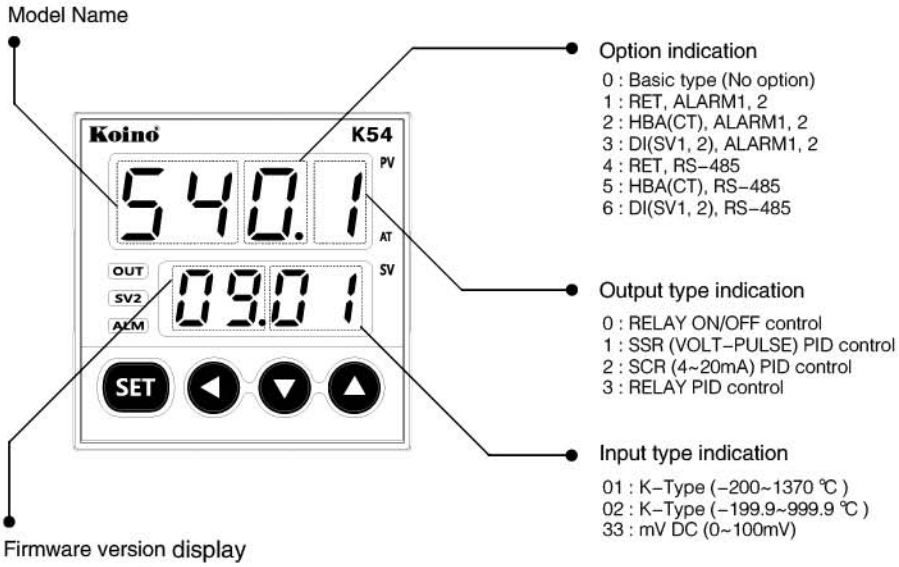
1) Default values at the point of manufacture

The default input and output values of the product at the point of manufacture are as follows.
Input : K–Type (Sel. code 1) Output : SSR mode (Sel. code 1)
※ In the case of the basic model of K34–S00 only, when SSR(1) or SCR(2) is chosen as the output mode, Alarm 1 output will be in main relay. (Refer to page 8 for details)

2) 7 Segment display indications



3) Initial display on power supply (K54–SERIES basis)



8. Initial installation and minimum operation procedures

The following are the instructions for initial installation and minimum operation procedures.
Please read the contents of this manual, including the general functions outlined here, as thoroughly as possible before operating the device.

1) Check the external wiring diagram and specifications
(power supply and terminal arrangement)
2) Check input and output specifications!
The default setting for the K50 series at the point of manufacturer are as follows.
Input : K(CA) Type (setting code 1)
Output : SSR mode (setting code 1)
If you wish to change the input or the output type, please select the option you desire on the input group and the output group menus.
※ The input type settings must be configured first before changes to other set values are made. When the input type is changed, all other parameters (set values) are reverted to their factory default.
3) Select the desired set value (SV).
4) Please set auto-tuning or P, I, D values to suit the operating environment.
Auto-tuning is recommended except under special circumstances

Set value(SV) setting [in condition of Mvn = OFF (basic)]

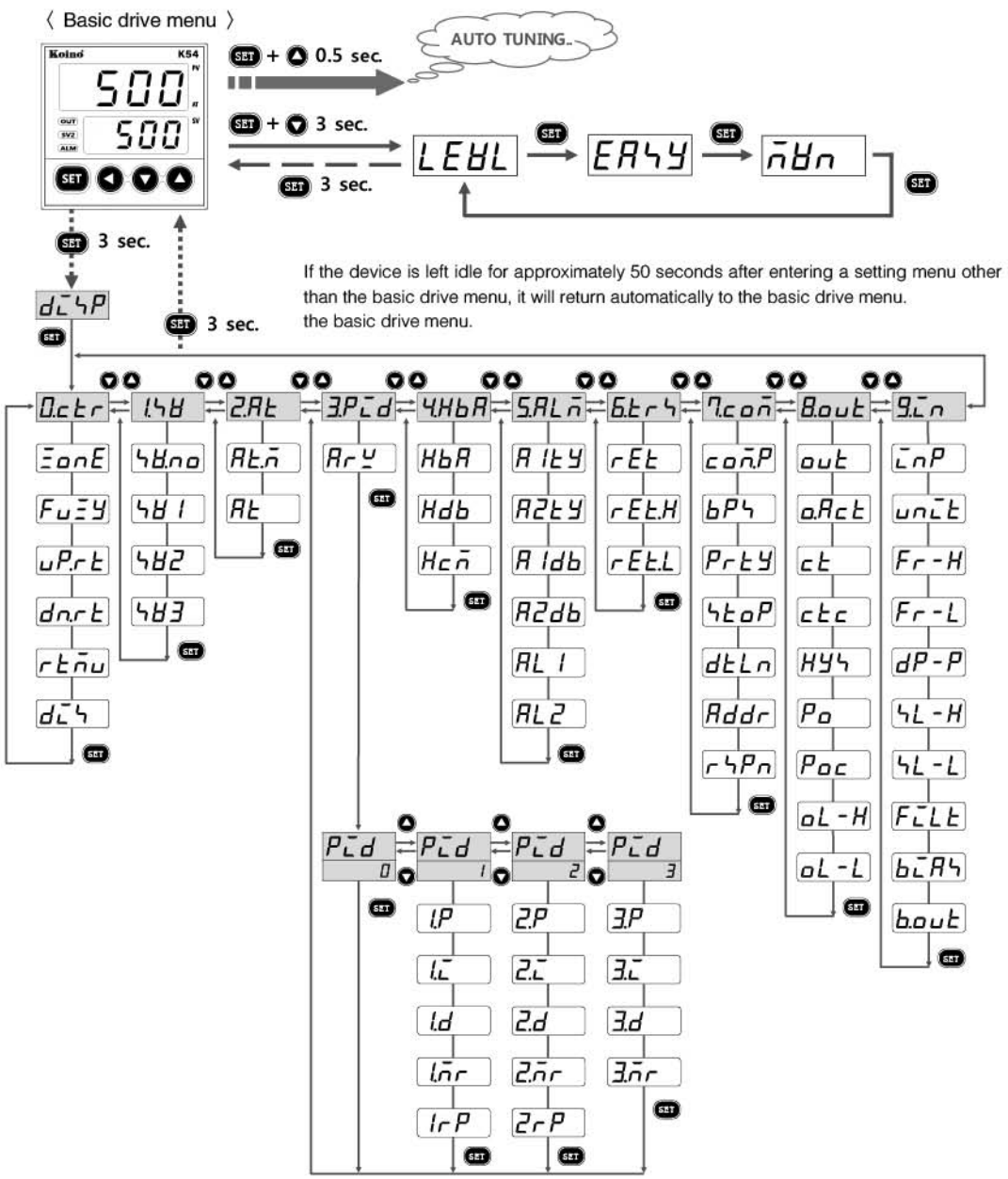
① Enter to setting mode by SET key
② Set a desired value by ◀ ▼ ▲ key
③ Store a value by SET key

Quick auto tuning

AT operation start: SET + ▲ 0.5 second
AT stop by perforce: SET + ▲ 0.5 second
AT command lamp (flash every 0.5sec.)

Tuning is required before operating for the first time. Set the target value(SV) in the range mainly used and run auto-tuning. When auto-tuning begins, the "auto-tuning command lamp" will flash every 0.5 second and will turn off upon completion of the tuning process. Please refrain from operating the keys while auto-tuning is in progress.

9. Flow Chart (Parameter structure)



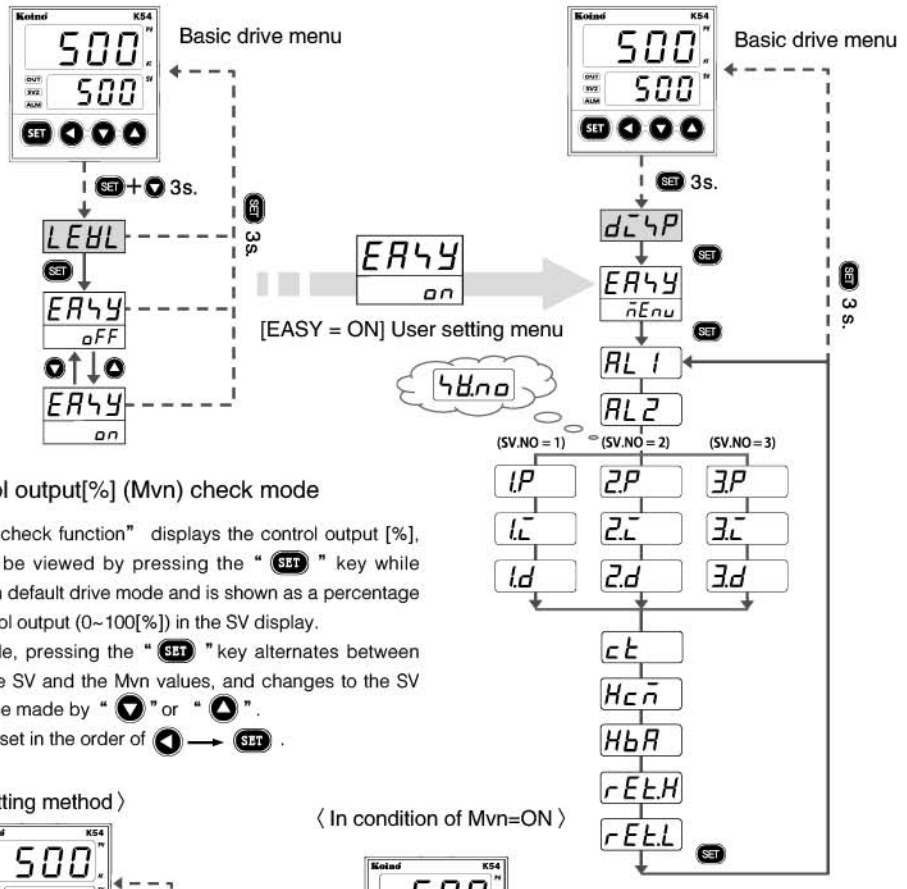
The full menu diagram above shows all control and setting menus on the K50 series, but during actual operations the menus that are the most relevant to the situation according to the options and the drive mode, providing a simpler user interface while retaining functionality.

10. Easy function & Safety function

1) Easy Menu

"Easy Menu" is displays the most frequently used functions of the K50 series, and hides the others.

〈 Setting method 〉

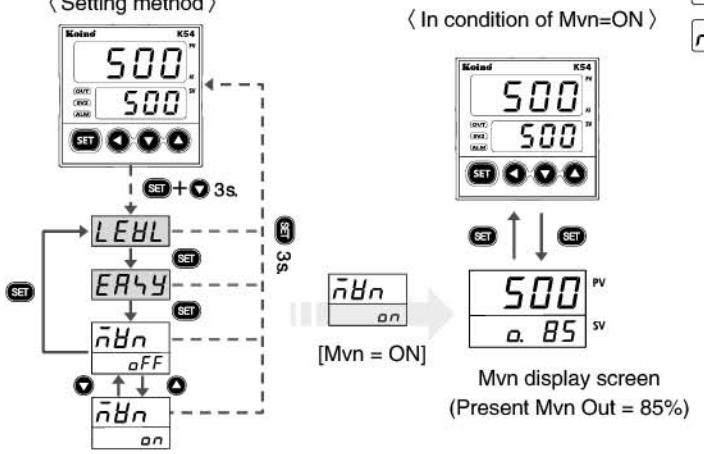


2) Control output[%] (Mvn) check mode

"Mvn [%] check function" displays the control output [%], which can be viewed by pressing the " SET " key while operating in default drive mode and is shown as a percentage of the control output (0~100[%]) in the SV display.
In this mode, pressing the " SET " key alternates between showing the SV and the Mvn values, and changes to the SV value can be made by " ▼ " or " ▲ ".
If required, set in the order of ◀ → SET .

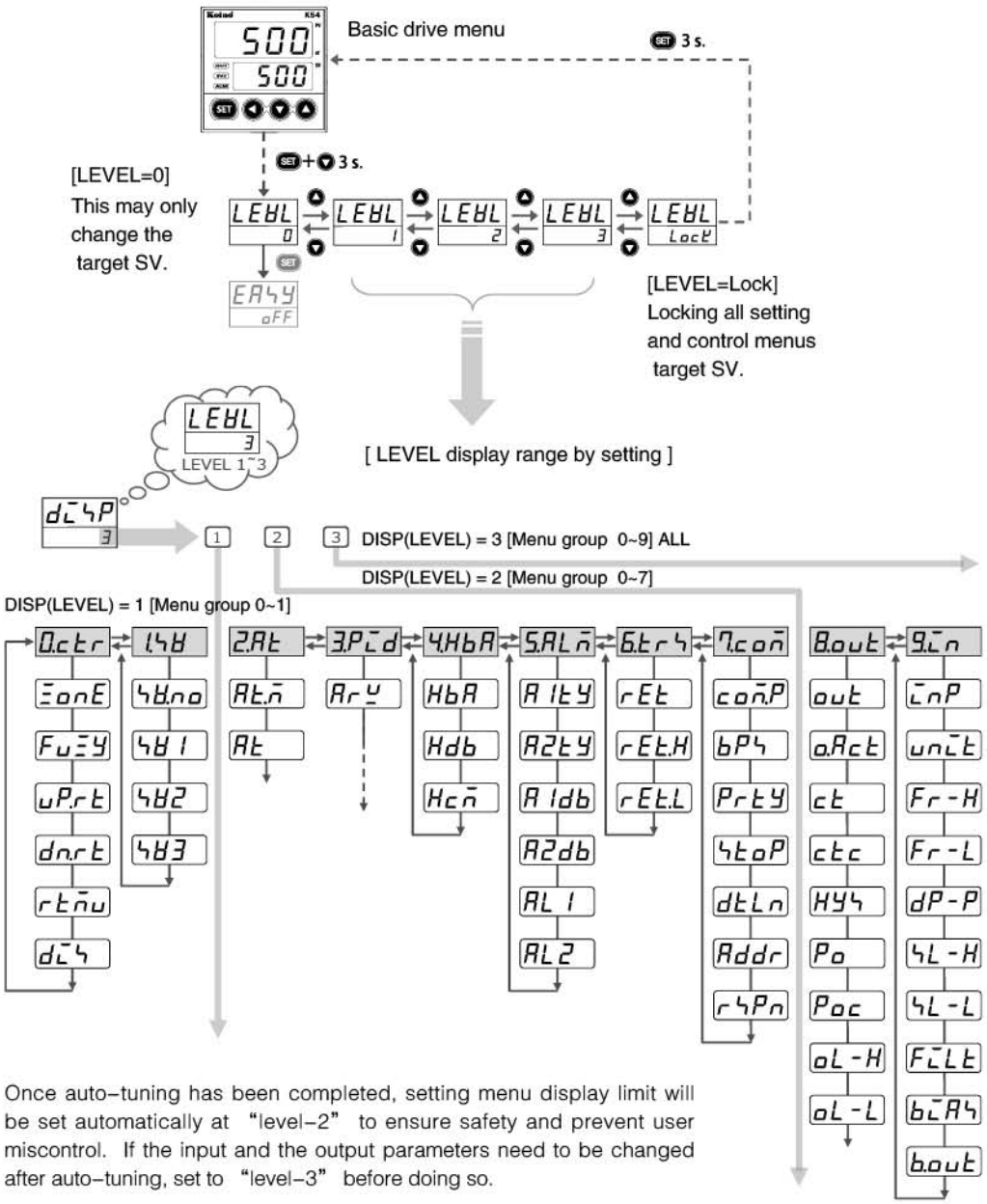
〈 Setting method 〉

〈 In condition of Mvn=ON 〉



3) Setting menu display limit (LEVEL) function

The setting menu display limit function limits the range displayed according to the level set in the control and the setting menus in the K50 series. This can be used, for example, to prevent user's miscontrol after all settings have been configured.



Once auto-tuning has been completed, setting menu display limit will be set automatically at "level-2" to ensure safety and prevent user miscontrol. If the input and the output parameters need to be changed after auto-tuning, set to "level-3" before doing so.

11. Functions of each setting group

[0] Control group setting

Control zone, fuzzy function, and ramp function may be selected, and the fuzzy function works only in PID control mode. In addition, as shown in Table 1, the 3 set values (SV1, SV2, SV3) preset by the two external contact inputs may be selected and controlled

Display	Description	Setting range	Condition	Initial value
0.ctr	Enter to control group	—	—	—
ZonE	Control zone selection	OFF / ON	Always	OFF
FuZy	Fuzzy function selection	OFF / ON	PID control	OFF
uP.rt	Initial rising temp. setting (Ramp function)	OFF / EUS (0 ~ 100 %)	Always	OFF
dn.rt	Initial drop temp. setting (Ramp function)	OFF / EUS (0 ~ 100 %)	Always	OFF
rtnu	Time (Hour/Minute) unit selection (Ramp function)	HOUR / MIN	Always	HOUR
dCh	External contact input ON/OFF switch	OFF / ON	D I option	OFF

※ EU : An engineering unit in compliance with the input range

ex) Input selection no. : 01 (K–TYPE)

EU 0 % = –200
EU 100 % = 1370

EUS 0 % = 0
EUS 100 % = 1570

1) Digital input switch (DIS): This function selects whether to use direct input switch.

※ Please use a non–voltage contact (relays, switches) for direct input. If a non–contact device such as a semiconductor are used, please operate within the ranges
ON = under 1KΩ, OFF = over 100KΩ.

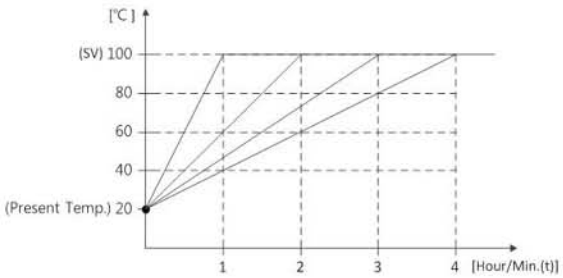
Target set value on External contact input (DIS=ON)

DIS election	SV selection mode by external contact signal		
OFF	No external contact signal		
ON	extenal signal / Display selection	SV2	SV3
	Display the SV1	OFF	OFF
	Display the SV2	ON	OFF
	Display the SV3	ON	ON

2) Control zone (ZONE): In an environment with large temperature fluctuations, the optimal PID value may vary according to the temperature range. This function allows 3 separate temperature ranges to be set in order to control the PID value in each of them.

3)Fuzzy : The K54 series is equipped by default with an S–PID unique to Temcoline, and separate fuzzy or ARW functions are usually not required, so this can be kept off most of the time. Use under special circumstances or when external disruptions cause repeated

4) Ramp function : This controls the incline toward the initial set values (SV1, SV2, SV3). To use this function, set the time at the initial temperature increase and decrease settings, or define the desired initial temperature increase or decrease per hour or minute. Once this has been set, a steady incline from the starting temperature to the set values will be maintained.



For example,
when the desired SV is set as 100 ℃ , the initial temperature increase as (UP. RT) 20 ℃ , and the time unit (RTMU) as in minutes, the incline to the SV will be at 20℃ per minute.

⬅ ※ Refer to left graph!

[1] Set value(SV) group setting

With the SV group, the 3 control set values (SV1, SV2, SV3) must be set before they can be selected and controlled as desired by direct input signal or by the internal menu.

※ In the case that direct input signal is used to control, the direct input switch (DIS) must be on. If the switch is off, the selection will be made by the set value number(SV no).

Display	Description	Setting range	Condition	Initial value
1.SU	Enter to set value setting group	—	—	—
SU.no	Set value number selection	1 / 2 / 3	Always	1
SU 1	Set value 1 (SV1) setting	EU (0.0 ~ 100.0 %)		EU (0.0%)
SU2	Set value 2 (SV2) setting	EU (0.0 ~ 100.0 %)		EU (0.0%)
SU3	Set value 3 (SV3) setting	EU (0.0 ~ 100.0 %)		EU (0.0%)

[2] Auto tuning(AT) group setting

Before the PID temperature controller can be used for the first time, the P, I, D values must be tuned. The auto–tuning function finds the optimal value by tuning automatically according to the load factor and other conditions.

Please make sure that the controller is tuned before using it for the first time, by defining the set values in the most frequently used range and running auto–tuning. When auto–tuning begins, the "auto–tuning command lamp" will flash every 0.5 second and will turn off upon completion of the tuning process. Please refrain from operating the keys while auto–tuning is in progress. The K50 series is able to perform several kinds of auto–tuning.

To make auto–tuning easier, the Quick–AT function, which allows the command to be executed with a simple external key combination.

Display	Description	Setting range	Condition	Initial value
2.AT	Enter to auto tuning	—	PID control	—
AT.n	Auto tuning (AT) type selection	Standard / Low	PID control	STD
AT	Auto tuning (AT) start selection	OFF / 1 / 2 / 3 / Auto	PID control	OFF

This product performs optimally when auto-tuning is executed in the STD mode according to the S-PID algorithm. We recommend that you operate the product in the STD mode.

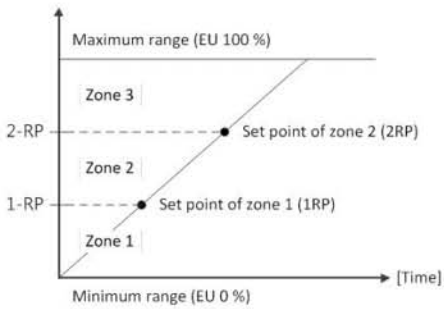
1) **Types of auto-tuning (AT)** : The K50 temperature controller has two tuning methods, standard auto-tuning (STD; based on the set value) and low-SV tuning (LOW: SV - 10%). Under normal conditions, the standard auto-tuning is recommended.
2) **Start auto-tuning** : This menu starts the auto-tuning process. Select the number of the SV that you wish to tune (SV1 → "1", SV2 → "2", SV3 → "3"), and auto-tuning will begin, making automatic calculations which will be stored under the P, I, D values of the corresponding SV.
   When set on AUTO,
   SV1~3 will be auto-tuned consecutively if in the control group ZONE is set as off. If ZONE is on, groups 1, 2, and 3 will be created based on the ranges set in 1RP and 2RP of the PID group, and the results will each be stored under the PID groups 1, 2, and 3.

[3] P.I.D group setting

This is used to view the PID and ARW values produced by auto-tuning in the auto-tuning groups, and to change the values manually.

1) **In the PID selection group,** press the "SET" key to set automatically or manually the anti-reset wind-up ARW value. Pressing again the "SET" key will display the PID selection mode, where you may choose to view the group PID parameters by selecting 0~3.
   For example, when "0" is selected in the PID mode, no PID values will be shown. Use the "▲" key to select "1" and then press the "SET" key to view the PID values for group 1. Selecting "2" and "3" will display the values for groups 2 and 3 respectively. (This is intended to preven t accidentally mishandling the settings)

2) Manual reset (MR) is displayed when the integral value set at OFF, and it is used to manually remove control offsets.
3) When the control group zone selection mode is on, 2 zone location settings may be made to control 3 zones.
4) The "n" in the table next page indicates that the number may be from 1 to 3.



This product provides optimal control when ARW is in automatic mode according to the S-PID algorithm. We recommend that you used the product in the automatic mode.
The ARW function is actually seldom required with S-PID.

Display	Description	Setting range	Condition	Initial value
3.PId	Enter to P.I.D setting group	—	PID control	—
Ar U	Anti Reset Wind–up setting	Auto / 50.0 ~ 200.0 %	PID control	AUTO
PId	P.I.D group selection	0 / 1 ~ 3	Always	0
n.P	n. Proportional (P)	0.1(D–TYPE : 0.0) ~ 999.9 %	PID group selection	3.0 %
n.I	n. Integral time (I)	OFF / 1 ~ 6000 sec.	Always	240 sec.
n.d	n. Differential time (D)	OFF / 1 ~ 6000 sec.	Always	60 sec.
n.nr	n. Manual reset (M.R)	–5.0 ~ 105.0 %	Integral time OFF	50.0 %
n.Pc	n. Proportional band of cooling side (P)	0.0 (ON/OFF control) 0.1 ~ 999.9 %	Heating/ Cooling type	3.0 %
n.Ic	n. Integral time of cooling side (I)	OFF / 1 ~ 6000 sec.	Heating/ Cooling type	240 sec.
n.dc	n. Differential time of cooling side (D)	OFF / 1 ~ 6000 sec.	Heating/ Cooling type	60 sec.
n.db	n. Hysteresis band	–100.0 ~ 50.0 %	Heating/ Cooling type	3.0 %
n.rP	n. Zone position setting	EU(0) 〈 1.RP 〈 2.RP 〈 EU(100.0 %)	ZONE=ON	EU(100.0 %)

[4] Heater break alarm (HBA) group setting

In the HBA setting group, a dedicated Current transformer(CT) may be set to monitor the AC current in a heater and to provide warning in case of malfunction. The threshold current level of the HBA may be set, and it may also be used to monitor electrical consumption.
(AC Current transformer (CT) : CTL–6–S or an 800:1 all–purpose CT may be used.)

Display	Description	Setting range	Condition	Initial value
4.HbA	Enter to heater break alarm Setting group	—	Option	—
HbA	Current setting of HBA	OFF / 1 ~ 50 A	HBA option	OFF
Hdb	Hysteresis setting of HBA	0 ~ 50 A		1
Hcn	Measuring value of HBA	0 ~ 50 A		—

HBA is generated through alarm output 1, and "alarm #1 type selection" must be set on code 21 in order for HBA to function.
HBA cannot be used when control output is in SCR mode (4~20mA).

[5] Alarm (Alarm 1, 2) group setting

The K50 series has two separate alarm outputs, and in the setting group, alarms may be chosen among 21 types, and the dead band (hysteresis) for the alarm output may be set.

Please find the alarm code with the desired function in the "Alarm types and codes table" on the next page and use it to set the alarm output type in the settings mode.

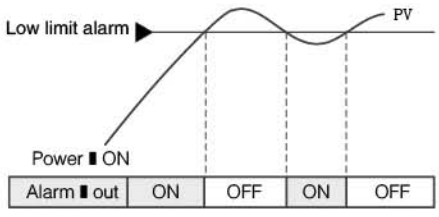
Display	Description	Setting range	Condition	Initial value
5.ALn	Enter to alarm setting group	—	Always	—
A1ty	Alarm 1 output selection	OFF / 1 ~ 21	Always	1
A2ty	Alarm 2 output selection	OFF / 1 ~ 20	Alarm option	2
A1db	Hysteresis of alarm 1 output	EUS (0.0 ~ 100.0 %)	Always	EUS (0.5%)
A2db	Hysteresis of alarm 2 output		Alarm option	EUS (0.5%)
AL 1	Alarm 1 output value setting	PV alarm, Deviation alarm EU (−100.0 ~ 100.0 %)	Always	EU (100.0%)
AL2	Alarm 2 output value setting		Alarm option	EU (0.0%)

The HBA will be generated through alarm output #1 (when A1TY = 21).
This means that HBA may be set only through alarm output #1.

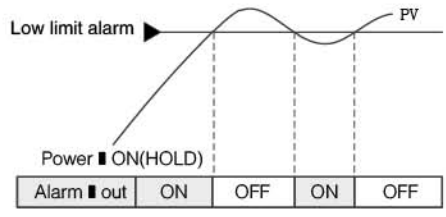
1) Hold function

When a low alarm is set and during temperature is rising, an unnecessary low alarm may be happen. The hold function may be used to eliminate such problems.
The hold function allows the low alarm to be ignored automatically until the temperature rises above the alarm threshold level for the first time when electricity is first turned on.

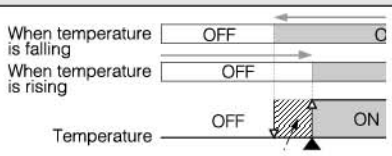
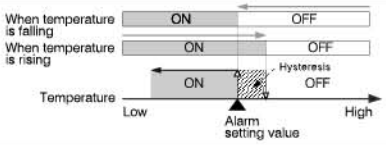
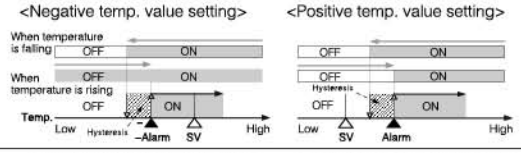
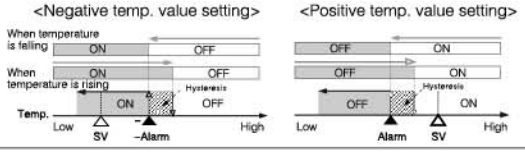
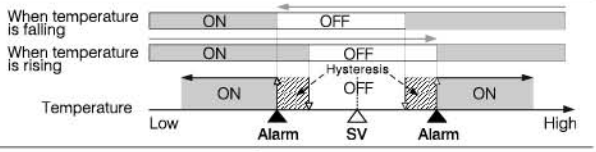
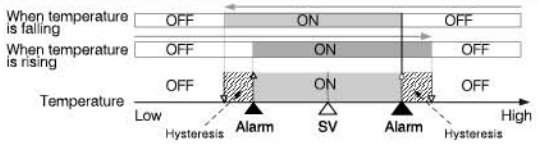
Hold function: None



Hold function

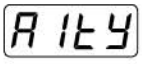


2) Alarm output type and Selection code

Code no.	Alarm type	Alarm output operation
01	Absolute value upper-limit	
09	(Inverted output)	
11	with Hold function	
19	with hold function (Inverted)	
02	Absolute value lower-limit	
10	(Inverted output)	
12	with Hold function	
20	with hold function (Inverted)	
03	Upper-limit deviation	
05	(Inverted output)	
13	with hold function	
15	with hold function (Inverted)	
04	Lower-limit deviation	
06	(Inverted output)	
14	with hold function	
16	with hold function (Inverted)	
07	Upper & Lower-limit deviation	
17	Upper & Lower-limit deviation with hold	
08	Upper & Lower-limit deviation in range	
18	Upper & Lower-limit deviation in range with hold	
21	Heater break alarm (HBA1)	Refer to HBA ! (ALARM1 only)

When alarm type reverse-correspondence is selected for alarm type and code, please be aware that when the alarm lamp turns on, the contact output will be off.

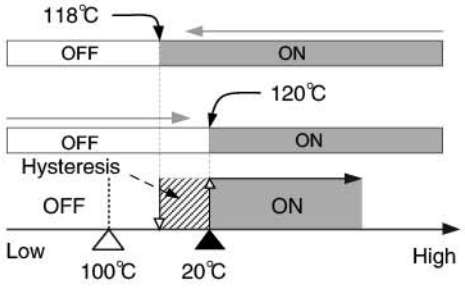
Example of Alarm output 1 setting



Alarm type (Upper-limit deviation) = 03

Hysteresis (Dead band) = 2 ℃

Alarm setting value = 20 ℃

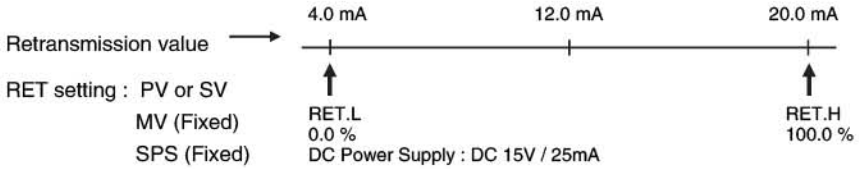


(When Set value (SV) = 100 ℃)

[6] Retransmission group setting

In the retransmission output mode, process value (PV), set value (SV), output amount (MV), or sensor power supply (SPS) may be chosen, and the output will be generated in direct current of 4~20mA. (SPS is DC15V/25mA)

Display	Description	Setting range	Condition	Initial value
6.trn	Enter to retransmission setting group	—	Option	—
rEt	Retransmission type or SPS selection	PV / SV / MV / SPS	Option	PV
rEt.H	Highest limit of retransmission	TC or RTD : Fr–H~Fr–L Voltage : SL–H~SL–L (But, RET.H 〉 RET.L)	PV or SV selection	EU (100.0%)
rEt.L	Lowest limit of retransmission			EU (0.0%)



[7] Communication group setting

Display	Description	Setting range	Condition	Initial value
7.con	Enter to communication setting group	—	Optional	—
con.P	Protocol selection (PC–Link, TL–Link, Modbus	HSTD / HSUM / H–TL MODA / MODB		H–TL
bPS	Baud rate selection (B.P.S)	600 / 1200 / 2400 / 4800 / 9600 [BPS]		9600 BPS
PrtY	Parity check selection	NONE / EVEN / ODD		NONE
StoP	Stop bit selection	1–bt(bit) / 2–bt(bit)		1–bt
dtLn	Data Length selection	7–bt(bit) / 8–bt(bit)		8–bt
Addr	Address selection	1 ~ 99 (Max. 32 devices)		1
rSPn	Response time selection	0 ~ 10 (Response time = Handling time + Response time) × 10ms		1

The K50 series has a totally insulated input–output structure.
A maximum of 32 devices may be connected to it, but this number may vary according to the site and the line conditions.

1) Communication protocols in detail

■ HSTD / HSUM
PC-Link is used by some in Korea, developed by 2 corporations.
■ H-TL (TL-Link)
This is Koino' s own protocol.
The multi-remote surveillance program, which is included in the optional communications package for the K50 series, uses this protocol. (For the reference, this program has advanced recording functions)
■ MODA (Modbus-ASCII)
This ASCII-based protocol is commonly used in the industry, and is easy to use.
■ MODB (Modbus-RTU)
This binary-based protocol is the most widely used standard protocol in the industry, and has a high speed.

2) Modbus protocol and K50 series

The Modbus communication protocol function code in the K50 series is comprised of a function code that reads and writes D-REGISTER, and another that searches for Loop-Back.
For more information, please refer to the separately distributed Koino protocol, or contact us by our website or our customer service center

[Modbus protocol support code]

Code	Description
03	D-REGISTER consecutive READ
06	Single D-REGISTER WRITE
08	DIAGNOSTICS (LOOP-BACK TEST)
16	D-REGISTER consecutive WRITE

The Modbus support device uses as address #400001~400999 in the16-bit holding register range, whichincludes 400001~465536.
When using a touchscreen for interface, the read/write addresses must be set at 400001 (D-Reg. 000) ~ 400700 (D-Reg. 699) for Pro-Face products.
For EasyView products, the device setting must be at 4x (16-bit), and the address at 001 (D-Reg. 000) ~ 700 (D-Reg. 699).

■ **Function Code 03 :** The device is capable of reading up to 32 consecutive D-Register contents.
■ **Function Code 06 :** The D-Register contents can be edited one at a time.
■ **Function Code 08 :** This can be used for self-diagnosis and testing purposes.
■ **Function Code 16 :** The device is capable of writing up to 32 consecutive D-Register contents.

In Modbus communication, the address will be designated as the real communication frame address +1. This is because the user may choose addresses from #400001 onward. (Example: #400001 = D-Reg. 000)

3) Modbus communication setting

■ Modbus-ASCII
COM.P : MODA, BPS : 9600, PRTY : EVEN, STOP : 1-BT(bit), DTLN(Fixed) : 7-BT(bit)
■ Modbus-RTU
COM.P : MODB, BPS : 9600, PRTY : EVEN, STOP : 1-BT(bit), DTLN(Fixed) : 8-BT(bit)

4) K50 D-REGISTER MAPPING

ADDRESS		PROCESS	CTRL	PGM	SV/PID	HBA/ALM	RET/COM	OUT/IN
Modbus		0	100	200	300	400	500	600
400 001	0				SV.NO	HBA1	RET	OUT
400 002	1	N.PV			SV1	H1DB	RET.H	O.ACT
400 003	2	N.SV	ZONE		SV2		RET.L	CT
400 004	3		FUZY		SV3			CTC
400 005	4		ARW					HYS
400 006	5	M.OUT			AT.M			PO
400 007	6		DIS		AT			POC
400 008	7							OL-H
400 009	8	PID.N	UP.RT					OL-L
400 010	9	ALM.S	DN.RT					
400 011	10		RTMU		1.P	A1TY	COM.P	INP
400 012	11				1.I	A2TY	BPS	UNIT
400 013	12				1.D		PRTY	FR-H
400 014	13				1.MR	A1DB	STOP	FR-L
400 015	14	HCM1			1.Pc	A2DB	DTLN	DP-P
400 016	15				1.Ic		ADDR	SL-H
400 017	16	ADE.S			1.Dc	AL-1	RSPN	SL-L
400 018	17	ERR.S			1.DB	AL-2		FILT
400 019	18	MOD.S			1.RP			BIAS
400 020	19							B.OUT
400 021	20				2.P			
400 022	21				2.I			
400 023	22				2.D			
400 024	23				2.MR			
400 025	24				2.Pc			
400 026	25				2.Ic			
400 027	26				2.Dc			
400 028	27				2.DB			
400 029	28				2.RP			
400 030	29							
400 031	30				3.P			
400 032	31				3.I			
400 033	32				3.D			
400 034	33				3.MR			
400 035	34				3.Pc			
400 036	35				3.Ic			
400 037	36				3.Dc			
400 038	37				3.DB			
..	..							
..	..							
400 099	99							

When using the communication options, please refer to the separately provided K50 series communication protocol manual. Only the basics are outlined here.

[8] Output group setting

The K50 series is categorized into S (standard) and D (heating/cooling) types, and has both multiple inputs and outputs. The user may select among relay, SSR, or SCR (4~20mA, DC) for output.

Display	Description	Setting range	Condition	Initial value
8.out	Enter to output setting group	—	—	—
out	Output type selection	0(on/off) / 1(SSR) / 2(SCR) / 3(Relay), (Refer to P8, 2–2.)	Always	1 (SSR)
o.Act	Output action selection	REV (Reverse action) / DIR (Direct action) (REV: Heating, DIR: cooling)	Always	REV
ct	Cycle time	1 ~ 1000 sec.	SSR / RELAY control	2 sec.
ctc	Cycle time of cooling output	1 ~ 1000 sec.	D–TYPE	20 sec.
HYS	Hysteresis (ON/OFF control)	EUS (0.0~100.0 %)	ON/OFF control	EUS (0.5%)
Po	Output 1 volume when input disconnected (OUT1)	–5.0 ~ 105.0 %	Always	0.0 %
Poc	Output 2 volume when input disconnected (OUT2)	–0.0 ~ 105.0 %	Heating & Cooling Model	0.0 %
oL-H	High limit of output	OL–L ~ 105.0 %	PID control	100.0 %
oL-L	Low limit of output	–0.5 % ~ OL–H	PID control	0.0 %

In PID control, output interval (Ct) will be 20 seconds if relay (code 3) is selected; when SSR (code 1) is selected, output interval will be automatically set at 2 seconds. You may change this manually

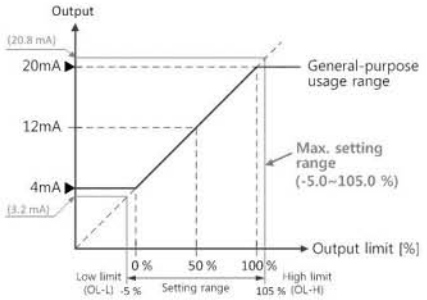
1) Setting output amount for the event that input has been cut off (Po)

If there is a problem with the input sensors or if for any reason the temperature controller does not function properly, this safety function shuts off internally controlled output or maintains steady output at a desired level.

2) Output limitation in high/low (OL–H, OL–L)

Since the K50 series uses the S–PID algorithm, this function is not necessary in most cases. This function may be used when special circumstances require limiting the output.

Using the default value (0~100.0%) is recommended.



[9] Input group setting

The K50 series supports a wide range of specifications, including 12 types of thermocouples (TC), 2 types of platinum resistance thermometers (RTD), and 3 types of current and voltage inputs. output.

Display	Description	Setting range	Condition	Initial value
9.Ln	Enter to input setting group	—	—	—
InP	Input type selection	1 ~ 33 (refer to P7, 2–1.)	Always	1
unIt	Input temperature unit selection	℃ / °F	TC or RTD input	℃
Fr-H	High limit	Within input range (refer to next page) but, Fr–H > Fr–L	Always	1370
Fr-L	Low limit		Always	–200
dP-P	Decimal point positioning (on voltage input)	0 / 1 / 2 / 3 (On voltage input)	On voltage input (mV, V)	1
SL-H	Scale high (On voltage input)	–1999 ~ 9999 But , SL–H > SL–L Decimal point positioning by DP–P	On voltage input (mV, V)	100.0
SL-L	Scale low (On voltage input)			0.0
FILt	Input digital filter	OFF / 1~120 sec.	Always	OFF
bIAS	Input correction	EUS (–100.0~100.0 %)	Always	EUS (0.0 %)
b.out	Burn–out selection	OFF / UP / DOWN	Always	UP

When the input type is changed, all parameters are reverted to their factory default. This means that before using the K50, the input type needs to be set first, after which other parameters can be configured. If the input settings are changed while in use, auto–tuning and other parameters need to be reconfigured.

1) Input type selection
This is the first thing that needs to be checked and set before using the K50, as the settings here will cause other parameters to be reset to their typically optimal values for that specific type. Please refer to the "Input type selection codes table" on the next page.

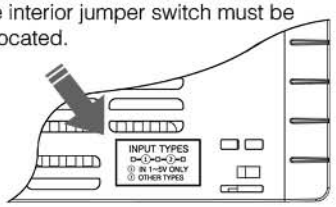
2) Input unit selection (℃ / ℉)
This selects the unit of temperature measurement to be displayed when using temperature sensors. The Celsius degree is set as the default, but it may be changed to the Fahrenheit degree. On products sold in Korea, the units are fixed to the Celsius degree in compliance with the regulations.

3) Setting decimal point position (DP–P), and free scale high and low limits (SL–H, SL–L)
This applies only when using voltage inputs (DC V, mV) or currents between 4 to 20mA (1~5V). The user may set ranges, units and decimal point position as desired. This can be used not only for temperatures but also for a number of other measurements, including humidity, pressure, and weight.

4) Digital input filter (FILT)
This function is useful when suboptimal environments cause noises or severe fluctuations, enabling a digital software filter. The filter's sensitivity may be set from off to 1~120 seconds. Please be careful when using this function, as it may affect the control-related algorithms.

5) Input value bias (BIAS)
This function allows the input values to be compensated. This function is useful, for example, when sensors cannot be placed at desired locations, or when several different thermometers are used in conjunction. The values may be compensated to extent

■ Input type selection codes table

Input type	Signal	Setting Code	Temperature range	Accuracy	Remarks
Thermocouple (T.C)	K	1	-200 ~ 1370	±0.3% of F.S +1Digit	* F.S is max. value to min. value of each range * Digit is minimum of display ① 0~400℃ range : ± 10% of F.S+1Digit
		2	-199.9 ~ 999.9		
	J	15	-200 ~ 1000		
		3	-199.9 ~ 999.9		
	E	16	-200 ~ 1000		
		4	199.9 ~ 999.9		
	T	5	-199.9 ~ 400.0		
	R	6	0 ~ 1700		
	B ①	7	0 ~ 1800		
	S	8	0 ~ 1700		
	L	17	-200 ~ 900		
		9	-199.9 ~ 900.0		
	N	10	-200 ~ 1300		
	U	11	-199.9 ~ 400.0		
	C (W5)	12	0 ~ 2300		
	D (W3)	13	0 ~ 2400		
RTD	JPt100 Ω (JIS,KS)	20	-199.9 ~ 500.0		
		22	-200 ~ 500		
	Pt100 Ω (DIN,IEC)	21	-199.9 ~ 640.0		
		23	-200 ~ 640		
Voltage (VDC/mVDC)	0~100 mV DC	33	0 ~ 100mV DC		
	-10~20 mV DC	32	-10 ~ 20 mV DC		
	1~5V DC	30	1~5V DC	※ When using 1~5V input (30), the interior jumper switch must be relocated. 	
Current	4~20mA DC	30	When using current input, use the resistor 250Ω on input terminal.		

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